



Performance Analysis of Acquisition Algorithms for Navic

N. Alivelu Manga

Abstract: Indian Regional Navigation Satellite System (IRNSS), is an indigenous navigation system designed and developed by ISRO (Indian Space Research Organization). It is named as NavIC, Navigation with Indian Constellation by Indian Prime Minister. NavIC is designed to have seven satellite constellation that provides reliable position, navigation and timing services over India. The focal modules of NavIC receiver are acquisition, tracking and navigation unit. Among them, acquisition is the data processing unit for detecting satellite signals and their corresponding code phase and carrier frequency. In this paper, various acquisition algorithms like Serial search and Parallel Code Phase search algorithms are analyzed and compared with Cooley-Tukey FFT algorithm and sub-sampled Fast Fourier transform (ssFFT). The results obtained in MATLAB shows that the acquisition computation time for ssFFT based NavIC receiver is faster than parallel FFT acquisition and the Cooley-Tukey FFT IRNSS acquisition algorithm is faster and provides better code phase and carrier frequency values compared to serial search acquisition algorithm.

Keywords—IRNSS, NavIC, acquisition, parallel code phase search algorithm, serial search acquisition algorithm, ssFFT, Cooley-Tukey FFT.

I. INTRODUCTION

Indian Regional Navigation Satellite System provides position, velocity and time over Indian region. It is developed ISRO and coined as NavIC by Prime Minister of India. The IRNSS project was approved by government of India in June 2006 with a sanction of 1420 Cr (Bhaskaranarayana, A, 2008). The IRNSS constellation consists of 7 satellites of which, three are in GEO stationary and four are in GSO synchronous orbits. The IRNSS provide two services namely Standard Position Service (SPS) and Restricted Service (RS). The main modules of NavIC receiver are acquisition, tracking and navigation unit. Among them, acquisition is the data processing unit for detecting satellite signals and their corresponding code phase and carrier frequency. This paper is planned into six sections. SPS signal generation is discussed in Section II. Section III describes the receiver architecture. Section IV describes the signal conventional acquisition algorithms and ssFFT and Cooley-Tukey acquisition algorithms. Section V shows the simulation results of the explained acquisition algorithms and their performance comparisons and conclusions are presented in Section VI

Revised Manuscript Received on December 30, 2019.

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II. SPS SIGNAL GENERATION

In the process of generation of L5 signal, P-code and navigation data are together multiplied.

The next step is the application of BPSK (Binary Phase Shift Keying) modulation with the incoming carrier signal. After that, C/A (Coarse/Acquisition) code is multiplied with navigation data, then application of BPSK modulation with 90degrees phase shifted version of incoming carrier signal. Obtained results from the two modulators are added get L5 signal of frequency 1175.45MHz (Fig. 1). To generate L5 signal of frequency 1176.45MHz, a common frequency signal of frequency, $f_0=10.23\text{MHz}$ is used.

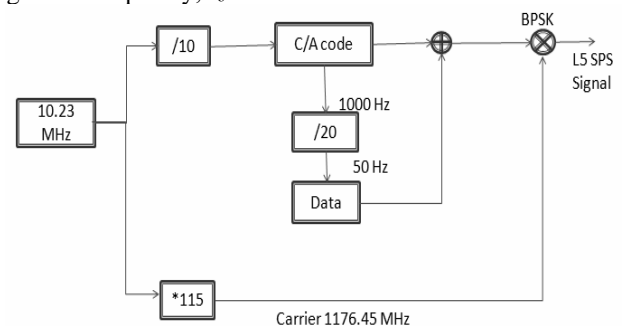


Fig. 1 SPS signal generator Block diagram

The modulo-2 (\oplus) addition gives a signal with values $\{1,0\}$ which is then BPSK modulated with carrier signal to obtain a L5 signal with values $\{-1,1\}$. The chipping rate for C/A code is considered as 1.023 MHz and navigation data bit rate is 50 Hz.

A unique C/A code is utilized by each of the satellite for the implementation of CDMA. The C/A codes are generated using pseudorandom noise (PRN) codes, also known as Gold codes. Two Linear Feedback Shift Registers (LFSR), G1 and G2 each of 10 bits, generate maximum length PRN codes having a length of $2^{10} - 1$ bits. The length of each generated code is 1023 chips. The code chipping rate used is 1.023 Mcps. The polynomials G1 and G2 used for SPS code generation are defined as given below:

$$G1(X) = 1 + X^3 + X^{10}$$

$$G2(X) = 1 + X^2 + X^3 + X^6 + X^8 + X^9 + X^{10}$$

These polynomials are analogous to the ones used for GPS C/A signal. These polynomials are implemented by using Maximum Length Feedback Shift Registers (MLFSR) each of length 10 bits. The initial state of G2 register provides the chip delay. The all bits of the G1 register are initialized to 1. Then, the bits of these two registers are exclusive-OR'ed to obtain the final PRN sequence of length 1023 chips. For all 7 satellites, the time period of the PRN sequence is 1 millisecond.



III. IRNSS RECEIVER ARCHITECTURE

IRNSS receiver is a system where the Signal In Space (SIS) is processed to determine user's position velocity and time. The functions of various sections of IRNSS receiver (Fig.2) in brief are:

- a) **Antenna and preamplifier:** The L5/S1 frequency band signals are detected by the smart antenna and it converts the wave energy into an electrical current, amplifies the signal strength and passes on the signal receiver electronics. Voltage induced by IRNSS signal in the antenna is sent to the preamplifier.
- b) **RF/IF Section:** The RF signal is mixed with a locally generated sinusoidal signal to down convert IRNSS signal to a lower frequency IF signal. IF signal contains code and data signals from the original RF signal with low carrier frequency.
- c) **Acquisition :** The process of Acquisition detects satellite signal coming from a given IRNSS satellite and provides coarse values of the code phase and the carrier frequency.
- d) **Tracking:** It refines the values produced by acquisition and tracks their changes continuously. It mainly consists of code tracking and carrier tracking loops.
- e) **NAV unit:** The role of an NAV unit block is to compute the IRNSS basic measurements: pseudo range, carrier phase and Doppler shift (or its pseudo range rate version).

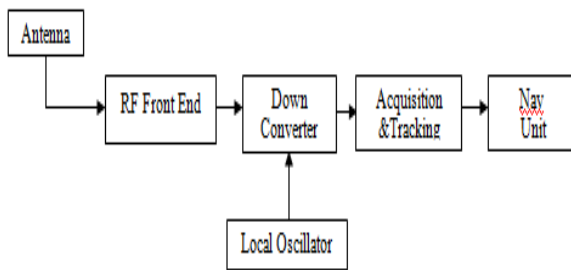


Fig.2 IRNSS Receiver Architecture

IV. ACQUISITION ALGORITHMS

From the acquisition process, satellite signal is detected and its corresponding coarse values of code phase and carrier frequency are estimated. There are several algorithms for acquisition GNSS/IRNSS signals including Serial search or time domain analysis acquisition algorithm, Parallel code phase search or FFT based algorithm, Parallel frequency code phase search acquisition.

A. Serial Search Acquisition Algorithm

Serial search acquisition is a simple and is a time domain acquisition algorithm. The process of serial search acquisition is shown in Fig.3. In this locally generated PRN code sequences are multiplied with locally generated replica of the carrier signal. Initially, the received IRNSS signal is multiplied with locally generated PRN sequence. Then, the result is multiplied by a local carrier signal to wipe off the carrier signal from the incoming signal. A in-phase signal I is generated by multiplication with in phase carrier signal replica, and multiplication with 90 degrees phase-shifted carrier signal replica, the quadrature signal Q is generated. The resulted I and Q signals are combined. This is done based on the length of one PRN code, and are squared and added finally. Code phase value is inferred from the serial search

acquisition which gives the correlation between the locally generated signal with that of the incoming signal.

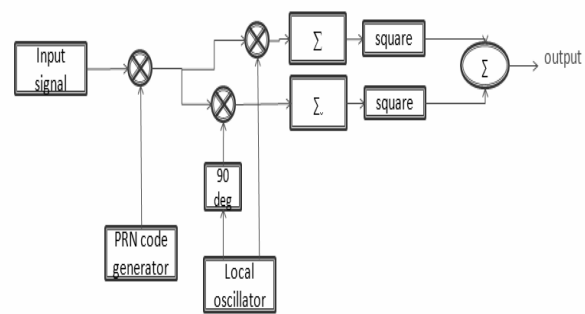


Fig.3 Serial Acquisition

B. Parallel Code Phase Search Acquisition Algorithm

Parallel Code Phase Search Acquisition Algorithm is Fast Fourier Transform based acquisition algorithm and frequency domain type. In this particular technique, acquisition is done parallel in a code phase dimension to speed up the acquisition process significantly. The received IF signal and the local carrier signal are multiplied together. The in-phase (I) signal is generated by multiplication with in phase signal and quadrature (Q) signal is generated by multiplication with a quad phase-shifted version of the signal,. These signals (I,Q) are combined to result in a complex input to the FFT function. The PRN code, generated for a specific satellite is changed into the frequency domain and complex conjugated. Then, the IF signal and PRN code are perform multiplication in the frequency domain. After that, The result is changed into the time domain by applying an inverse Fourier transform (Fig 4).

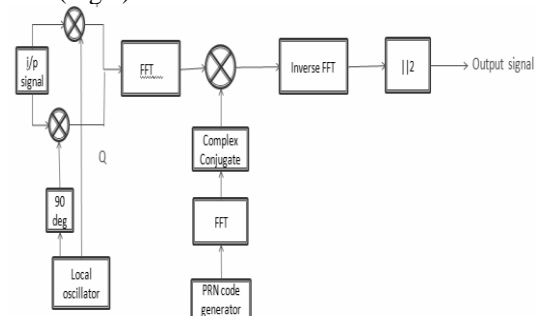


Fig. 4 Parallel Code Phase Search Acquisition

Then, the correlation between the input and the PRN code represented by the absolute value of this inverse Fourier transform. The index of the peak presented in the output of correlation, indicates the PRN code phase of the incoming signal.

C. Sub Sampled Fast Fourier Transform Acquisition

In this, the signal is down sampled by a factor 'd', a decimator which is an integer. The IFFT shown in Fig.5 is sparse in the time domain, i.e., there will be only one spike in time domain. Hence, it can be performed in sub-linear time and also require less number of samples as input to compute the sparse IFFT. As a result, there is no need to perform a full length computations on the received signal and one can get all of its frequency samples. Here, the number of frequency samples that are required to perform the sparse inverse FFT need to be computed.

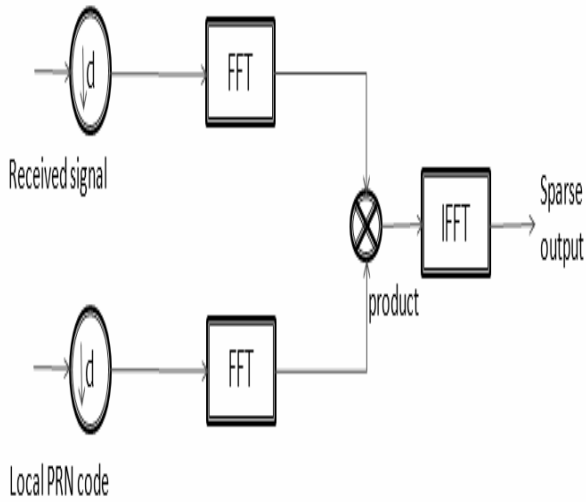


Fig.5 Acquisition using sub sampled Fast Fourier Transform

D. FFT Acquisition Algorithm using Cooley Tukey FFT

As shown in Fig.6, the principle of Cooley-Tukey algorithm applied to compute N point DFT by decomposing into smaller size DFTs, which results in reduction of time of FFT computation.

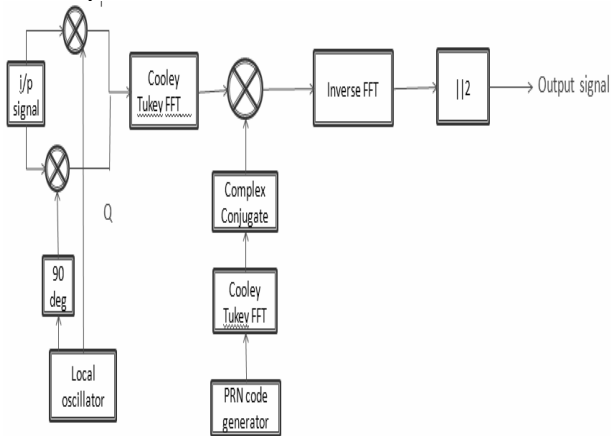


Fig.6 Block diagram of Acquisition based on Cooley Tukey FFT Algorithm

V. RESULTS AND DISCUSSION

IRNSS SPS signal is generated for L5 signal and C/A code for different satellites (L5 band) are simulated in MATLAB. The various acquisition algorithms like serial search and parallel code phase search, to find code phase and carrier frequency of received IRNSS signals are simulated in MATLAB. For this, the sampling frequency used is 56 MHz, and carrier frequency is 16.221MHz. Apart from these algorithms, Sub Sampled Fast Fourier Transform Acquisition and FFT Acquisition Algorithm using Cooley Tukey FFT are also analyzed. IRNSS SPS signal for 0.05 milliseconds is shown Fig. 7. In Fig. 8,9,10,11,12,13 and 14 x- axis indicates code phase, y- axis indicates frequency bin and z- axis indicates magnitude. Doppler shift is calculated using (frequency bin*125-5000).The acquisition results for satellite 4 using serial search method is with Doppler shift 500Hz and Code phase 23290 shown in Fig. 8. For satellite 4, the acquisition results using Parallel Code phase search method are presented in Fig 9 with Doppler shift 250Hz and Code phase is 853 for down sampled 8184 samples and for

56000*2 samples Code phase calculated is 23857. Fig 10,11,12 and 13 shows Acquisition results for satellite 4 for down sample factor 2,3,4 and 6 respectively. In Fig. 10, Doppler shift is 250 Hz and Code phase is 426. In Fig. 11, Doppler shift 250 Hz and Code phase is 284. In Fig. 12 Doppler shift is 250Hz and Code phase is 213. In Fig. 13, Doppler shift is 250 Hz and Code phase is 142. Using Cooley Tukey FFT, 8184 samples are divided into 88 and 93 samples. Fig. 14 shows Acquisition results for satellite 4 using Cooley Tukey FFT with Doppler shift is 250 Hz and code phase is 853. The Table 1 shows the acquisition results for available data using serial search method. The acquisition results using Parallel Code Phase Search Acquisition Algorithm are given in the Table 2. acquisition results of satellite 4 using sub sampled FFT are presented in Table 3. Table 4 shows Acquisition results using Cooley Tukey FFT method. Table 5 shows Comparison of acquisition results for satellite 4 using different acquisition algorithms.

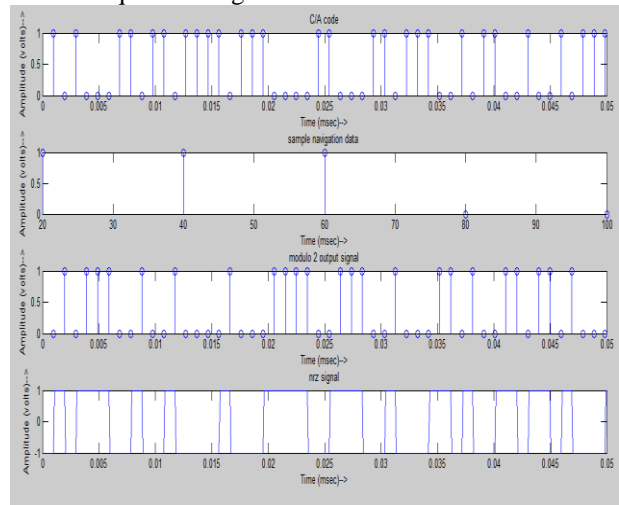


Fig.7 IRNSS SPS generation

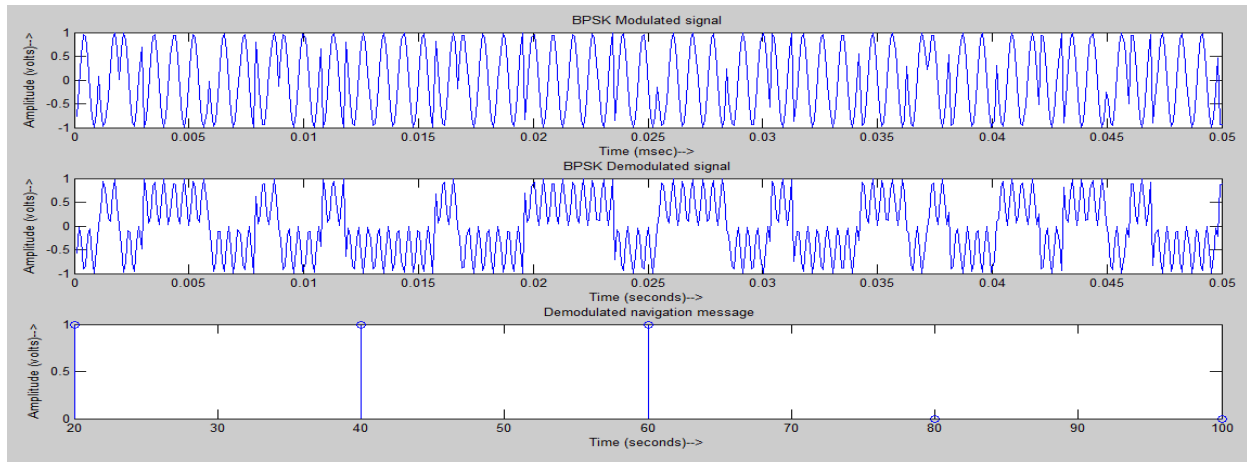


Fig.8 SPS generation for 0.05 milliseconds

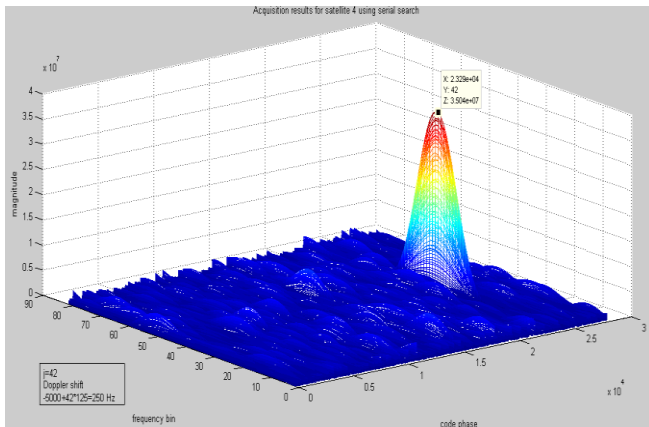


Fig.9 Acquisition results for satellite 4 using serial search method

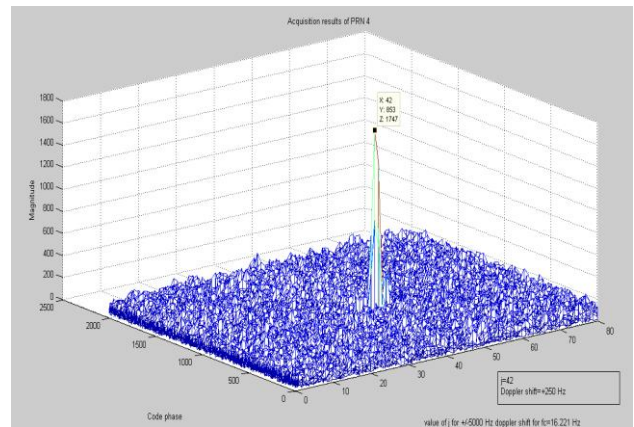


Fig.10 Acquisition results for satellite 4 using parallel code phase method

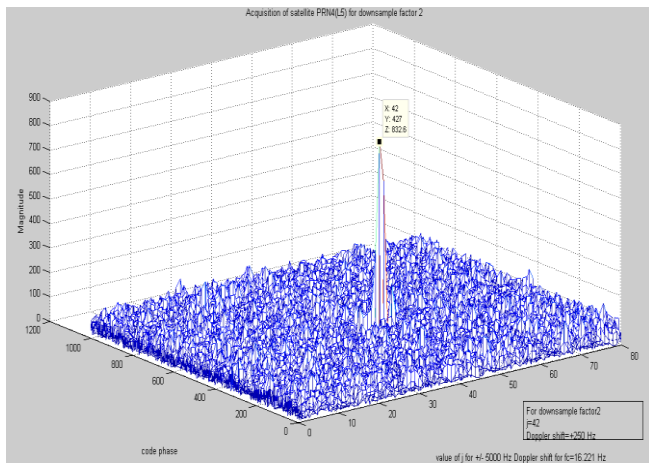


Fig.11 Acquisition results of satellite 4 for down sample factor 2

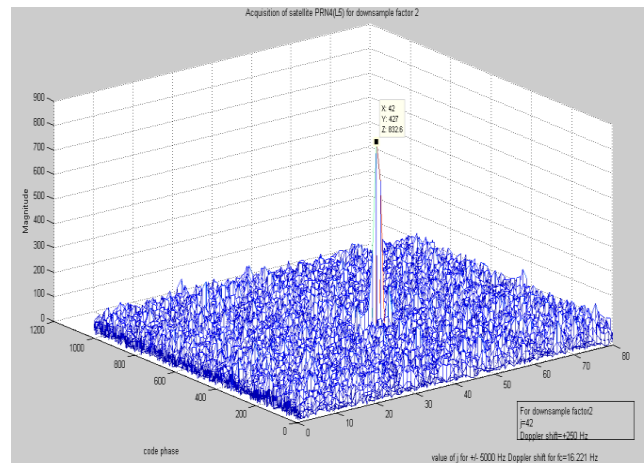


Fig.12 Acquisition results of satellite 4 for down sample factor 3

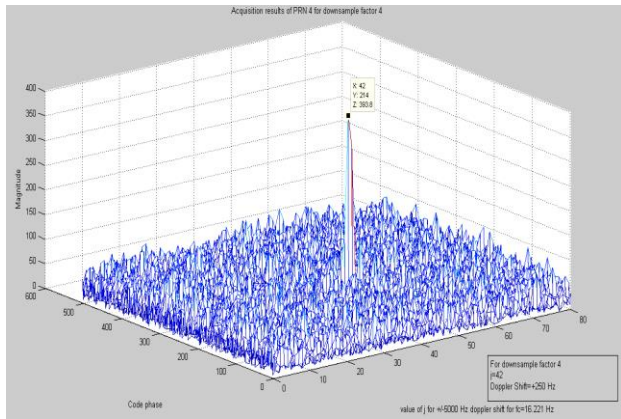


Fig.13 Acquisition results of satellite 4 for down sample factor 4

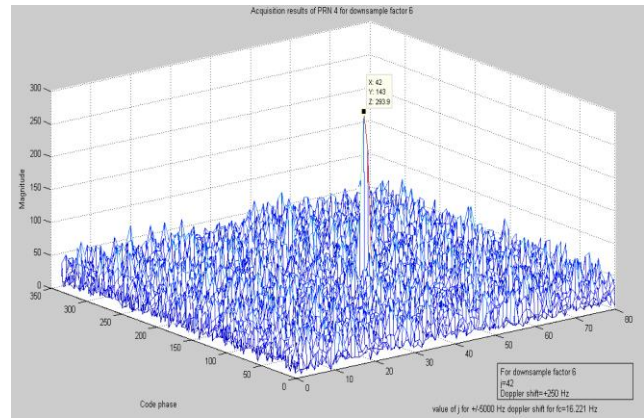


Fig 14 Acquisition results of satellite 4 for down sample factor 6

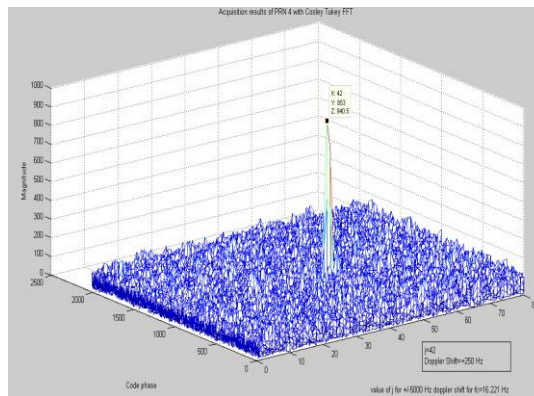


Fig.15 Acquisition results for satellite 4 using Cooley Tukey FFT

Table 1: Acquisition results for different satellites using serial search method

S.No.	L5-SPS G2	Code phase	Doppler shift(Hz)	Carrier frequency (Hz)
1	1110010111	55220	-1500	16219500
2	0110010000	30766	+250	16221500
3	0010110001	54927	-125	16221500
4	0100111010	23290	+250	16221500
5	0000110111	39820	-125	16221500
6	1101011000	2270	-125	16221500
7	0010100000	29315	+375	16221500

Table 2: Acquisition results for different satellites using Parallel Code Phase Search Acquisition Algorithm

S.No.	L5-SPS G2	Code phase in 8184 samples	Code phase in 56000*2 samples	Doppler shift(Hz)
1	1110010111	2020	56533	-2125
2	0110010000	1126	31501	+250
3	0010110001	2009	56225	-125
4	0100111010	853	23857	+250
5	0000110111	1457	40769	-250
6	1101011000	85	2353	-125
7	0010100000	1073	30017	-125

Table 3: Acquisition Results of satellite 4 using sub sampled FFT

S.No.	d	Code phase	Carrier frequency(Hz)	time (sec)	d*log(d)
1	-	853	16221250	17.1007	
2	2	426*2+1=853	16221250	16.4522	2
3	3	284*3+1=853	16221250	16.3571	4.75
4	4	213*4+1=853	16221250	16.2946	8
5	6	142*6+1=853	16221250	15.878274	15.51

Table 4: Acquisition results for different satellites using Cooley Tukey FFT method

S.No.	L5-SPS G2	Code phase in 8184 samples	Code phase in 56000*2 samples	Doppler shift(Hz)
1	1110010111	2020	56533	-2125
2	0110010000	1126	31501	+250
3	0010110001	2009	56225	-125
4	0100111010	853	23857	+250
5	0000110111	1457	40769	-250
6	1101011000	85	2353	-125
7	0010100000	1073	30017	-125

Table 5: Comparison of acquisition results for satellite 4 using different acquisition algorithms

Acquisition Algorithm	Code phase	Carrier frequency(MHz)	Time (sec)
Serial search	23290	16.221500	1079.7422
Parallel Code Phase Search Acquisition Algorithm	23857	16.221250	17.7001
FFT Acquisition Algorithm using Cooley Tukey FFT	23857	16.221250	119.01

VI. CONCLUSION

In this paper, various acquisition algorithms for NavIC signals are simulated and analyzed. It is observed that, Parallel FFT(17.7001 s) is faster than Serial Search acquisition algorithm(1079.7422 s).Reduction in the acquisition time and computation complexity is observed by the exploitation of properties of sparse FFT, Fourier transform and decimator and by the use of sub sampled FFT. From the simulation, it is observed that the acquisition time is decreased from (17.7001 s) to (15.878274 s) for down sampling factor 6 without change in the code phase and Doppler frequency shift. The Cooley-Tukey algorithm is also analyzed, it is noticed that, in comparison with Serial search Acquisition algorithm (1079.7422 s),Parallel Code Phase Search(17.7001 s) and Cooley Tukey FFT(119.01 s) Acquisition algorithm is faster.

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