

Remarks on $\gamma^{\hat{\Omega}^*}$ -open sets and minimal $\gamma^{\hat{\Omega}^*}$ -open sets

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Abstract: Aim of this paper is to define $\gamma^{\hat{\Omega}^*}$ -open sets in a topological space and obtain their basic properties. Also, we define minimal $\gamma^{\hat{\Omega}^*}$ -open sets in a space and study the impact of two minimal $\gamma^{\hat{\Omega}^*}$ -open sets in a space with $\hat{\Omega}$ -regular operation. However, the roll of minimal $\gamma^{\hat{\Omega}^*}$ -open sets in $\gamma^{\hat{\Omega}^*}$ -locally finite space has been discussed.

Keywords : $\gamma^{\hat{\Omega}^*}$ -open set, $\gamma^{\hat{\Omega}^*}$ -Interior, $\gamma^{\hat{\Omega}^*}$ -Closure, minimal $\gamma^{\hat{\Omega}^*}$ -open set, $\gamma^{\hat{\Omega}^*}$ -locally finite space.

I. INTRODUCTION

In a topological space, the notion of minimal open sets had been introduced by Nakaoka and Oda[4] in 2001. In 2012, Lellis Thivagar et al.[1] introduced the class of $\hat{\Omega}$ -closed sets in a space which is independent of closed sets. Recently, [3] operation on the class of $\hat{\Omega}$ -open sets have been introduced and studied. In this paper, we introduce the class of $\gamma^{\hat{\Omega}^*}$ -open sets and investigate their basic properties in terms of its closure. However, Nakaoka's idea of minimal open sets has been extended to $\gamma^{\hat{\Omega}^*}$ -open sets and some of its elementary properties have been derived. Moreover, the behaviour of minimal $\gamma^{\hat{\Omega}^*}$ -open sets in a $\gamma^{\hat{\Omega}^*}$ -locally finite space has been investigated.

II. PRELIMINARIES

Some definitions and results that are used in this paper have been given in this section. Always X or (X, τ) denotes a topological space on which no separation axioms assumed,

Revised Manuscript Received on December 16, 2019.

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unless otherwise stated. For any subset A of X , the closure (res.interior) of A is denoted by $cl(A)$ (res. $int(A)$).

Definition 2.1 [2] A subset A of a topological space (X, τ) is called a **semi-open set** if $A \subseteq cl(int(A))$. $SO(X)$ denotes the set of all semi-open sets in (X, τ) . Its complement is known as **semi-closed set** on X .

Definition 2.2 ([1], Definition 3.1) Let (X, τ) be a topological space. A is said to be **$\hat{\Omega}$ -closed set** if $\delta cl(A) \subseteq U$ when $A \subseteq U$, where U is a semi-open subset of X . The complement of $\hat{\Omega}$ -closed set is an $\hat{\Omega}$ -open set. The family of all $\hat{\Omega}$ -closed sets in a space (X, τ) is denoted by ${}^{\tau}\hat{\Omega}$. Also $\hat{\Omega}O(X, \tau)$ or $\hat{\Omega}O(X)$ (resp. $\hat{\Omega}C(X, \tau)$ or $\hat{\Omega}C(X)$) denotes the set of all $\hat{\Omega}$ -open sets (resp. $\hat{\Omega}$ -closed sets) on the space X .

Definition 2.3 ([3], Definition 3.1) A function $\gamma : \hat{\Omega}O(X, \tau) \rightarrow P(X)$ is called an **operation on $\hat{\Omega}O(X, \tau)$** , if $U \subseteq \gamma(U)$ for every set $U \in \hat{\Omega}O(X, \tau)$. For any operation $\gamma, \gamma(X) = X$, and $\gamma(\emptyset) = \emptyset$.

Definition 2.4 ([3], Definition 3.3) A non-empty set A of X is called **$\gamma^{\hat{\Omega}}$ -open set** if for each $x \in A$, there exists an $\hat{\Omega}$ -open set U such that $x \in U$ and $\gamma(U) \subseteq A$. The complement of $\gamma^{\hat{\Omega}}$ -open set is a $\gamma^{\hat{\Omega}}$ -closed set. The set of all $\gamma^{\hat{\Omega}}$ -open subsets of a topological space (X, τ) is denoted by $\tau_{\gamma^{\hat{\Omega}}}$.

Definition 2.5 ([3], Definition 3.15) Let (X, τ) be a topological space. An operation γ is said to be **$\hat{\Omega}$ -regular** if for every pair of sets $U, V \in \hat{\Omega}O(X, x)$, there exists an $\hat{\Omega}$ -open set W containing x such that $\gamma(W) \subseteq \gamma(U) \cap \gamma(V)$.

Remark 2.6 ([1], Remark 5.2) From the definition and Theorem 4.16, arbitrary intersection of an $\hat{\Omega}$ -closed sets in a topological space (X, τ) is an $\hat{\Omega}$ -closed set in (X, τ) , $\hat{\Omega}cl(A)$ is the smallest $\hat{\Omega}$ -closed set containing A .

Theorem 2.7 ([3], Theorem 3.5) Arbitrary union of $\gamma^{\hat{\Omega}}$ -open sets is a $\gamma^{\hat{\Omega}}$ -open set in a topological space.

Proposition 2.8 ([3], Proposition 3.8) Every $\gamma^{\hat{\Omega}}$ -open set is an $\hat{\Omega}$ -open in a space X .

Proposition 2.9 ([3], Proposition 3.17) Intersection



of any two $\mathcal{Y}_{\hat{\Omega}}^*$ -open sets is a $\mathcal{Y}_{\hat{\Omega}}^*$ -open in a space with an $\hat{\Omega}$ -regular operation on $\hat{\Omega}O(X, \tau)$.

III. $\mathcal{Y}_{\hat{\Omega}}^*$ -OPEN SETS

Definition 3.1 A subset A of a space (X, τ) is said to be a $\mathcal{Y}_{\hat{\Omega}}^*$ -open subset of X , if the following two axioms hold:

- i) A is a $\mathcal{Y}_{\hat{\Omega}}^*$ -open subset of X .
- ii) For any $x \in A$, there exists an $\hat{\Omega}$ -closed set F containing x such that $F \subseteq A$.

The complement of a $\mathcal{Y}_{\hat{\Omega}}^*$ -open set is a $\mathcal{Y}_{\hat{\Omega}}^*$ -closed set in X . However, $\mathcal{Y}_{\hat{\Omega}}^*O(X)$ (resp. $\mathcal{Y}_{\hat{\Omega}}^*C(X)$) denotes the set of all $\mathcal{Y}_{\hat{\Omega}}^*$ -open sets (resp. $\mathcal{Y}_{\hat{\Omega}}^*$ -closed sets) on X and $\mathcal{Y}_{\hat{\Omega}}^*O(X, x)$ denotes the set of all $\mathcal{Y}_{\hat{\Omega}}^*$ -open sets containing x .

Example 3.2 Consider a space with $X = \{a, b, c, d\}$ and $\tau = \{\emptyset, \{a\}, \{c\}, \{a, b\}, \{a, c\}, \{a, b, c\}, \{a, c, d\}, X\}$. Define $\mathcal{Y}_{\hat{\Omega}}^*O(X, \tau) \rightarrow P(X)$ is defined by $\mathcal{Y}_{\hat{\Omega}}^*(\emptyset) = \emptyset, \mathcal{Y}_{\hat{\Omega}}^*(\{a\}) = \{a\}, \mathcal{Y}_{\hat{\Omega}}^*(\{c\}) = \{c\}, \mathcal{Y}_{\hat{\Omega}}^*(\{a, b\}) = \{a, b, c\}, \mathcal{Y}_{\hat{\Omega}}^*(\{a, c\}) = \{a, c, d\}, \mathcal{Y}_{\hat{\Omega}}^*(\{a, b, c\}) = \{a, b, c, d\}, \mathcal{Y}_{\hat{\Omega}}^*(\{a, c, d\}) = \{a, c, d\}, \mathcal{Y}_{\hat{\Omega}}^*(X) = X$. Here, \mathcal{Y} is an operation on $\hat{\Omega}O(X, \tau)$.

$\tau_{\mathcal{Y}_{\hat{\Omega}}^*} = \{\emptyset, \{a\}, \{c\}, \{a, c\}, \{a, b, c\}, X\}$, $\hat{\Omega}C(X) = \{\emptyset, \{d\}, \{b, d\}, \{c, d\}, \{a, b, c, d\}, X\}$. Here, \emptyset and X are the only $\mathcal{Y}_{\hat{\Omega}}^*$ -open subsets of X .

Proposition 3.3 In a space (X, τ) , the following statements hold.

- i) Every $\mathcal{Y}_{\hat{\Omega}}^*$ -open subset is a $\mathcal{Y}_{\hat{\Omega}}^*$ -open set.
 - ii) Every $\mathcal{Y}_{\hat{\Omega}}^*$ -open set is an $\hat{\Omega}$ -open set.
- Proof.** i) It follows straightly from the definition.
ii) It follows by combining i) and By Proposition 2.8

Remark 3.4 From the following example, it is seen that there are some $\mathcal{Y}_{\hat{\Omega}}^*$ -open subsets which fail to be the $\mathcal{Y}_{\hat{\Omega}}^*$ -open sets in a space (X, τ) .

Example 3.5 Let $X = \{a, b, c\}, \tau = \{\emptyset, \{a\}, \{a, b\}, X\}$; $\hat{\Omega}O(X) = \{\emptyset, \{a\}, X\}$; $\hat{\Omega}C(X) = \{\emptyset, \{b, c\}, X\}$.

Define an operation $\mathcal{Y}: \hat{\Omega}O(X) \rightarrow P(X)$ as follows:
 $\mathcal{Y}(W) = \begin{cases} W & \text{if } W = \{a\} \text{ or } \emptyset \\ X & \text{Otherwise} \end{cases}$

Here, $\tau_{\mathcal{Y}_{\hat{\Omega}}^*} = \{\emptyset, \{a\}, X\}$; $\mathcal{Y}_{\hat{\Omega}}^*O(X) = \{\emptyset, X\}$.
Now $\{a\} \in \tau_{\mathcal{Y}_{\hat{\Omega}}^*}$ but $\{a\} \notin \mathcal{Y}_{\hat{\Omega}}^*O(X)$.

Theorem 3.6. Arbitrary union of $\mathcal{Y}_{\hat{\Omega}}^*$ -open sets in a space (X, τ) is a $\mathcal{Y}_{\hat{\Omega}}^*$ -open set.

Proof. Let $\{U_i / i \in I\}$ be any collection of $\mathcal{Y}_{\hat{\Omega}}^*$ -open sets in a space X and let $U = \bigcup_{i \in I} U_i$. By Theorem 2.7, U is a $\mathcal{Y}_{\hat{\Omega}}^*$ -open

subset of X . Let $x \in U$ be arbitrary. Then $x \in U_i$ for some $i \in I$. Since U_i is a $\mathcal{Y}_{\hat{\Omega}}^*$ -open subset of X , there exist an $\hat{\Omega}$ -closed set F containing x such that $F \subseteq U_i \subseteq U$. Therefore, U is a $\mathcal{Y}_{\hat{\Omega}}^*$ -open subset of X .

Remark 3.7. The intersection of any two $\mathcal{Y}_{\hat{\Omega}}^*$ -open sets is not always a $\mathcal{Y}_{\hat{\Omega}}^*$ -open set as seen from the following example.

Example 3.8. Let $X = \{a, b, c\}$ and $\tau = P(X)$. Define an operation $\mathcal{Y}: \hat{\Omega}O(X) \rightarrow P(X)$ as follows:

$$\mathcal{Y}(W) = \begin{cases} W & \text{if } W = \{a, b\} \text{ or } \{a, c\} \text{ or } \emptyset \\ X & \text{Otherwise} \end{cases}$$

$\mathcal{Y}_{\hat{\Omega}}^*O(X) = \{\emptyset, \{a, b\}, \{a, c\}, X\}$. Here, the two sets $\{a, b\}$ and $\{a, c\}$ are $\mathcal{Y}_{\hat{\Omega}}^*$ -open sets but $\{a\}$ is not a $\mathcal{Y}_{\hat{\Omega}}^*$ -open in X .

Proposition 3.9. If U and V are $\mathcal{Y}_{\hat{\Omega}}^*$ -open sets in a space X , then $U \cap V$ is a $\mathcal{Y}_{\hat{\Omega}}^*$ -open set provided \mathcal{Y} is an $\hat{\Omega}$ -regular operation.

Proof. Let U and V be any two $\mathcal{Y}_{\hat{\Omega}}^*$ -open subsets of X . By Proposition 2.9, $U \cap V$ is a $\mathcal{Y}_{\hat{\Omega}}^*$ -open subset of X . Let $x \in U \cap V$ be arbitrary. Since U and V are $\mathcal{Y}_{\hat{\Omega}}^*$ -open subsets of X , there exists two $\hat{\Omega}$ -closed sets F_1 and F_2 containing x such that $F_1 \subseteq U$ and $F_2 \subseteq V$. By choosing F as $F_1 \cap F_2$, F is an $\hat{\Omega}$ -closed set containing x such that $F \subseteq U \cap V$. Therefore, $U \cap V$ is a $\mathcal{Y}_{\hat{\Omega}}^*$ -open subset of X .

$\mathcal{Y}_{\hat{\Omega}}^*$ -Closure and $\mathcal{Y}_{\hat{\Omega}}^*$ -Interior of a set have been defined in the usual manner as follows:

Definition 3.10. $\mathcal{Y}_{\hat{\Omega}}^*$ -closure of any subset A of a space (X, τ) is denoted by $\mathcal{Y}_{\hat{\Omega}}^*cl(A)$ and defined by

$$\mathcal{Y}_{\hat{\Omega}}^*cl(A) = \bigcap \{F / F \in \mathcal{Y}_{\hat{\Omega}}^*C(X) \text{ such that } A \subseteq F\}.$$

Always $\mathcal{Y}_{\hat{\Omega}}^*cl(\emptyset) = \emptyset$; $\mathcal{Y}_{\hat{\Omega}}^*cl(X) = X$; $\mathcal{Y}_{\hat{\Omega}}^*cl(A)$ is a $\mathcal{Y}_{\hat{\Omega}}^*$ -closed subset of X and $\mathcal{Y}_{\hat{\Omega}}^*(\mathcal{Y}_{\hat{\Omega}}^*cl(A)) = \mathcal{Y}_{\hat{\Omega}}^*cl(A)$.

Definition 3.11. $\mathcal{Y}_{\hat{\Omega}}^*$ -interior of any subset A of a space (X, τ) is denoted by $\mathcal{Y}_{\hat{\Omega}}^*int(A)$ and defined by

$$\mathcal{Y}_{\hat{\Omega}}^*int(A) = \bigcup \{U / U \in \mathcal{Y}_{\hat{\Omega}}^*O(X) \text{ such that } U \subseteq A\}.$$

Always, $\mathcal{Y}_{\hat{\Omega}}^*int(\emptyset) = \emptyset$; $\mathcal{Y}_{\hat{\Omega}}^*int(X) = X$ and $\mathcal{Y}_{\hat{\Omega}}^*int(A)$ is a $\mathcal{Y}_{\hat{\Omega}}^*$ -open subset of X .

Proposition 3.12. If U and V are any two subsets of a space X , then the following statements are true.

- i) $U \subseteq V \Rightarrow \mathcal{Y}_{\hat{\Omega}}^*int(U) \subseteq \mathcal{Y}_{\hat{\Omega}}^*int(V)$.
- ii) U is $\mathcal{Y}_{\hat{\Omega}}^*$ -open iff $U = \mathcal{Y}_{\hat{\Omega}}^*int(U)$.



iii) $U \subseteq V \Rightarrow \gamma_{\hat{\Omega}}^* cl(U) \subseteq \gamma_{\hat{\Omega}}^* cl(V)$

iv) U is $\gamma_{\hat{\Omega}}^*$ -closed iff $U = \gamma_{\hat{\Omega}}^* cl(U)$

v) $X \setminus \gamma_{\hat{\Omega}}^* int(U) = \gamma_{\hat{\Omega}}^* cl(X \setminus U)$

vi) $X \setminus \gamma_{\hat{\Omega}}^* cl(U) = \gamma_{\hat{\Omega}}^* int(X \setminus U)$

Proof. It follows from the definition.

Proposition 3.13. For any point x in a space X and for any subset A of X , $x \in \gamma_{\hat{\Omega}}^* cl(A)$ iff $U \cap A \neq \emptyset$ for any $U \in \gamma_{\hat{\Omega}}^* O(X, x)$

Proof. Assume that $x \in \gamma_{\hat{\Omega}}^* cl(A)$ and there exists a $\gamma_{\hat{\Omega}}^*$ -open set U containing x such that $U \cap A = \emptyset$. Now, $X \setminus U$ is a $\gamma_{\hat{\Omega}}^*$ -closed set such that $A \subseteq X \setminus U$. That is, $X \setminus U \in \{F/F \in \gamma_{\hat{\Omega}}^* C(X); A \subseteq F\}$. In particular, $\gamma_{\hat{\Omega}}^* cl(A) \subseteq X \setminus U$, a contradiction to $x \in \gamma_{\hat{\Omega}}^* cl(A)$. Conversely, on

contrary $x \notin \gamma_{\hat{\Omega}}^* cl(A) = \bigcap \{F/F \in \gamma_{\hat{\Omega}}^* C(X); A \subseteq F\}$. Then $x \notin F$ for some $\gamma_{\hat{\Omega}}^*$ -closed set F such that $A \subseteq F$. If U is chosen as $X \setminus F$, then U is a $\gamma_{\hat{\Omega}}^*$ -open subset of X such that $U \cap A = \emptyset$, a contradiction to hypothesis.

IV. MINIMAL $\gamma_{\hat{\Omega}}^*$ -OPEN SETS AND $\gamma_{\hat{\Omega}}^*$ -LOCALLY FINITE SPACE

Definition 4.1. A $\gamma_{\hat{\Omega}}^*$ -open subset U of a space X is said to be a **minimal $\gamma_{\hat{\Omega}}^*$ -open set** if \emptyset and U are the only $\gamma_{\hat{\Omega}}^*$ -open subsets of U .

Example 4.2 Let $X = \{a, b, c\}$ and $\tau = P(X) = \hat{\Omega}O(X, \tau)$. Define an operation $\gamma: \hat{\Omega}O(X) \rightarrow P(X)$ as follows:

$$\gamma(W) = \begin{cases} W & \text{if } W = \{a, b\} \text{ or } \{a, c\} \text{ or } \emptyset \\ X & \text{Otherwise} \end{cases}$$

$\gamma_{\hat{\Omega}}^* O(X) = \{\emptyset, \{a, b\}, \{a, c\}, X\} = \gamma_{\hat{\Omega}}^* O(X)$. Here $\{a, b\}$ and $\{a, c\}$ are minimal $\gamma_{\hat{\Omega}}^*$ -open sets in X .

Proposition 4.3. Let (X, τ) be any topological space. If U is a non-empty $\gamma_{\hat{\Omega}}^*$ -open subset of X such that $\gamma_{\hat{\Omega}}^* cl(U) = \gamma_{\hat{\Omega}}^* cl(V)$ for any non-empty subset V of U , then U is a minimal $\gamma_{\hat{\Omega}}^*$ -open set.

Proof. On contrary, U is assumed to be a non-minimal $\gamma_{\hat{\Omega}}^*$ -open subset of X such that $\gamma_{\hat{\Omega}}^* cl(U) = \gamma_{\hat{\Omega}}^* cl(V)$ for any non-empty subset V of U . By the definition of minimal open set, there exists a non-empty $\gamma_{\hat{\Omega}}^*$ -open set W such that $W \subsetneq U$. Choose $x \in U \setminus W$. Now W is a $\gamma_{\hat{\Omega}}^*$ -open set such that $x \notin W$. Therefore,

$W \cap \gamma_{\hat{\Omega}}^* cl(\{x\}) = \emptyset$ or $\gamma_{\hat{\Omega}}^* cl(\{x\}) \subseteq X \setminus W$. Now $\{x\}$ is a non-empty subset of U . By hypothesis, $\gamma_{\hat{\Omega}}^* cl(U) = \gamma_{\hat{\Omega}}^* cl(\{x\}) \subseteq X \setminus W$. However,

$W \subsetneq U \subseteq \gamma_{\hat{\Omega}}^* cl(U) = \gamma_{\hat{\Omega}}^* cl(\{x\}) \subseteq X \setminus W$ Which implies that $W \subseteq X \setminus W$, a contradiction.

Proposition 4.4. Let γ be an $\hat{\Omega}$ -regular operation in a space X . If U is a minimal $\gamma_{\hat{\Omega}}^*$ -open set and V is a $\gamma_{\hat{\Omega}}^*$ -open set then either $U \cap V = \emptyset$ or $U \subseteq V$.

Proof. Assume that $U \cap V = \emptyset$. By Proposition 3.9, $U \cap V$ is a $\gamma_{\hat{\Omega}}^*$ -open set. By the definition of minimal $\gamma_{\hat{\Omega}}^*$ -open sets, $U \cap V = V$. Thus $U \subseteq V$.

Proposition 4.5. Let γ be an $\hat{\Omega}$ -regular operation in a space X . If U and V are any two minimal $\gamma_{\hat{\Omega}}^*$ -open sets, then either $U \cap V = \emptyset$ or $U = V$

Proof. Assume that $U \cap V = \emptyset$. Apply Proposition 4.4 for both minimal $\gamma_{\hat{\Omega}}^*$ -open sets U and V . Then $U = V$.

Proposition 4.6. Let γ be an $\hat{\Omega}$ -regular operation in a space X and U be a minimal $\gamma_{\hat{\Omega}}^*$ -open set of X . Then for any $x \in U$, $U \subseteq V$ where V is any $\gamma_{\hat{\Omega}}^*$ -open set containing x .

Proof. Assume the contrary that there exists $x \in U$ such that $U \not\subseteq V$ for any $\gamma_{\hat{\Omega}}^*$ -open subset V containing x . By Proposition 3.9, $U \cap V$ is a $\gamma_{\hat{\Omega}}^*$ -open subset of X . As $x \in U \cap V$, $U \cap V \neq \emptyset$ such that $U \cap V \subseteq U$, a contradiction to U is a minimal $\gamma_{\hat{\Omega}}^*$ -open subset.

Proposition 4.7. If U is a minimal $\gamma_{\hat{\Omega}}^*$ -open subset of a space

$$X, \text{ then } U = \bigcap_{x \in U} \{V/V \in \gamma_{\hat{\Omega}}^* O(X, x)\}.$$

Proof. By Proposition 4.6, for any $x \in U$, $U \subseteq V$ for any $\gamma_{\hat{\Omega}}^*$ -open subset V containing x . Then $U \subseteq \bigcap \{V/V \in \gamma_{\hat{\Omega}}^* O(X, x)\}$. In particular,

$$\bigcap \{V/V \in \gamma_{\hat{\Omega}}^* O(X, x)\} \subseteq U$$

$$U = \bigcap \{V/V \in \gamma_{\hat{\Omega}}^* O(X, x)\}.$$

Proposition 4.8. Let γ be an $\hat{\Omega}$ -regular operation of a space X . If U is a minimal $\gamma_{\hat{\Omega}}^*$ -open subset of X , then for any $x \in X \setminus U$, and for any $\gamma_{\hat{\Omega}}^*$ -open set V containing x , either $V \cap U = \emptyset$ or $U \subseteq V$.

Proof. It follows from Proposition 4.4.

Proposition 4.9. Let γ be an $\hat{\Omega}$ -regular operation in a space X . If U is a non-empty minimal $\gamma_{\hat{\Omega}}^*$ -open subset of X , then $U \subseteq \gamma_{\hat{\Omega}}^* cl(V)$ for any non-empty subset V of U .

Proof. Let $x \in U$ be arbitrary and W be any $\gamma_{\hat{\Omega}}^*$ -open set

containing x . By Proposition 4.4, either $U \cap W = \emptyset$ or $U \subseteq W$. Since $x \in U \cap W$, the only possibility is $U \subseteq W$. Then, $V = U \cap V \subseteq W \cap V$. As $V \neq \emptyset, W \cap V \neq \emptyset$. By Proposition 3.13, $x \in \mathcal{Y}_{\hat{\Omega}}^*cl(V)$.

Characterization of minimal $\mathcal{Y}_{\hat{\Omega}}^*$ -open set in a space is given as follows.

Theorem 4.10. Let \mathcal{Y} be an $\hat{\Omega}$ -regular operation in a space X and U be any non-empty $\mathcal{Y}_{\hat{\Omega}}^*$ -open subset of X . Then the following statements are equivalent:

- i) U is a minimal $\mathcal{Y}_{\hat{\Omega}}^*$ -open set.
- ii) $U \subseteq \mathcal{Y}_{\hat{\Omega}}^*cl(V)$ for any non-empty subset V of U .
- iii) $\mathcal{Y}_{\hat{\Omega}}^*cl(U) = \mathcal{Y}_{\hat{\Omega}}^*cl(V)$ for any non-empty subset V of U .

Proof. i) \Rightarrow ii) It follows from Proposition 4.9.

ii) \Rightarrow iii) Let V be any non-empty subset of U . By hypothesis $U \subseteq \mathcal{Y}_{\hat{\Omega}}^*cl(V)$ and hence $\mathcal{Y}_{\hat{\Omega}}^*cl(U) \subseteq \mathcal{Y}_{\hat{\Omega}}^*(\mathcal{Y}_{\hat{\Omega}}^*cl(V)) = \mathcal{Y}_{\hat{\Omega}}^*cl(V)$. On the other hand, $V \subseteq U \Rightarrow \mathcal{Y}_{\hat{\Omega}}^*cl(V) \subseteq \mathcal{Y}_{\hat{\Omega}}^*cl(U)$.

iii) \Rightarrow i) On contrary, U is assumed to be a non-minimal $\mathcal{Y}_{\hat{\Omega}}^*$ -open subset. Then, a non-empty $\mathcal{Y}_{\hat{\Omega}}^*$ -open set V can be chosen such that $V \subsetneq U$. Having chosen $x \in U \setminus V$, $V \cap \mathcal{Y}_{\hat{\Omega}}^*cl(\{x\}) = \emptyset$ and hence $\mathcal{Y}_{\hat{\Omega}}^*cl(\{x\}) \subseteq X \setminus V$. But by hypothesis, $\mathcal{Y}_{\hat{\Omega}}^*cl(\{x\}) = \mathcal{Y}_{\hat{\Omega}}^*cl(U)$. It is concluded that $V \subseteq U \subseteq \mathcal{Y}_{\hat{\Omega}}^*cl(U) = \mathcal{Y}_{\hat{\Omega}}^*cl(\{x\}) \subseteq X \setminus V$, a contradiction.

Therefore, U is a minimal $\mathcal{Y}_{\hat{\Omega}}^*$ -open set.

Definition 4.11. A space X is said to be $\mathcal{Y}_{\hat{\Omega}}^*$ -locally finite space, if for every $x \in X$ there exists a finite $\mathcal{Y}_{\hat{\Omega}}^*$ -open set U in X such that $x \in U$. Every finite topological space is always $\mathcal{Y}_{\hat{\Omega}}^*$ -locally finite space.

Proposition 4.12. Every non-empty finite $\mathcal{Y}_{\hat{\Omega}}^*$ -open set in a space X contains some non-empty finite minimal $\mathcal{Y}_{\hat{\Omega}}^*$ -open set.

Proof. Let V be any non-empty finite $\mathcal{Y}_{\hat{\Omega}}^*$ -open set in X . If V is a minimal $\mathcal{Y}_{\hat{\Omega}}^*$ -open set in X , then it meets our requirement. Suppose that V is not a minimal $\mathcal{Y}_{\hat{\Omega}}^*$ -open set in X . Then, there exists a non-empty finite $\mathcal{Y}_{\hat{\Omega}}^*$ -open set W_1 such that $W_1 \subsetneq V$. If W_1 is a minimal $\mathcal{Y}_{\hat{\Omega}}^*$ -open set, then the condition is satisfied. If not, by proceeding like this we would arrive at a sequence of non-empty finite $\mathcal{Y}_{\hat{\Omega}}^*$ -open sets $W_1, W_2, \dots, W_n, \dots$ such that $\dots \subsetneq W_n \subsetneq W_{n-1} \subsetneq W_{n-2} \subsetneq \dots \subsetneq W_1 \subsetneq V$. Since V is finite, there exists $m \in \mathbb{N}$ such that W_m is a minimal $\mathcal{Y}_{\hat{\Omega}}^*$ -open set such that $W_m \subseteq V$. Hence the result holds.

Proposition 4.13. Let \mathcal{Y} be an $\hat{\Omega}$ -regular operation in a $\mathcal{Y}_{\hat{\Omega}}^*$ -locally finite space X . Then every non-empty $\mathcal{Y}_{\hat{\Omega}}^*$ -open set in a space X contains some non-empty finite minimal $\mathcal{Y}_{\hat{\Omega}}^*$ -open set.

Proof. Let V be any non-empty $\mathcal{Y}_{\hat{\Omega}}^*$ -open subset of X . Then choose $x \in V$. By the definition of $\mathcal{Y}_{\hat{\Omega}}^*$ -locally finite space, there exists a finite $\mathcal{Y}_{\hat{\Omega}}^*$ -open set U such that $x \in U$. Since U is finite, $U \cap V$ is also finite. By Proposition 3.9, $U \cap V$ is a finite $\mathcal{Y}_{\hat{\Omega}}^*$ -open set containing x . By Proposition 4.12, there exists non-empty finite minimal $\mathcal{Y}_{\hat{\Omega}}^*$ -open set W such that $W \subseteq U \cap V \subseteq V$.

Proposition 4.14. Let X be a topological space and \mathcal{Y} be an $\hat{\Omega}$ -regular operation on X . Then the following are true.

i) Let $V_\alpha, \alpha \in I$ be any $\mathcal{Y}_{\hat{\Omega}}^*$ -open set and U be a non-empty finite $\mathcal{Y}_{\hat{\Omega}}^*$ -open set in X . Then $U \cap \left(\bigcap_{\alpha \in I} V_\alpha\right)$ is a finite $\mathcal{Y}_{\hat{\Omega}}^*$ -open set.

ii) Let V_α be a $\mathcal{Y}_{\hat{\Omega}}^*$ -open set for any $\alpha \in I$ and V_β be a non-empty finite $\mathcal{Y}_{\hat{\Omega}}^*$ -open set for any $\beta \in J$. Then $\left(\bigcup_{\beta \in J} V_\beta\right) \cap \left(\bigcap_{\alpha \in I} V_\alpha\right)$ is a $\mathcal{Y}_{\hat{\Omega}}^*$ -open set.

Proof. i) Let V_α be a $\mathcal{Y}_{\hat{\Omega}}^*$ -open subset for any $\alpha \in I$ and U be a non-empty finite $\mathcal{Y}_{\hat{\Omega}}^*$ -open set in X . Since U is finite, $U \cap \left(\bigcap_{\alpha \in I} V_\alpha\right)$ is a finite set. Then, there exists a positive integer n

such that $U \cap \left(\bigcap_{\alpha \in I} V_\alpha\right) = U \cap \left(\bigcap_{i=1}^n V_{\alpha_i}\right)$. By Proposition 3.9, $U \cap \left(\bigcap_{\alpha \in I} V_\alpha\right)$ is $\mathcal{Y}_{\hat{\Omega}}^*$ -open set.

ii) Let U_α be a $\mathcal{Y}_{\hat{\Omega}}^*$ -open set for any $\alpha \in I$ and V_β be a non-empty finite $\mathcal{Y}_{\hat{\Omega}}^*$ -open set for any $\beta \in J$. By Theorem 3.6, $\left(\bigcup_{\beta \in J} V_\beta\right) \cap \left(\bigcap_{\alpha \in I} U_\alpha\right)$ is $\mathcal{Y}_{\hat{\Omega}}^*$ -open set. By (i), $\left(\bigcup_{\beta \in J} V_\beta\right) \cap \left(\bigcap_{\alpha \in I} U_\alpha\right)$ is $\mathcal{Y}_{\hat{\Omega}}^*$ -open set in X .

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