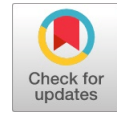


Rgδ-Continuous Functions and Their Properties in Topological Spaces



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Abstract: A continuity form of $rg\delta$ is offered in this commodity. The design of $rg\delta$ -irresolute functions and strongly $rg\delta$ -continuous functions are also discussed and its properties are investigated.

Keywords: $rg\delta$ -continuous, $rg\delta$ -Irresolute maps, strongly $rg\delta$ -continuous

I. INTRODUCTION

Many researchers have introduced the concepts of generalized continuous functions, gc-irresolute maps on topological spaces. [1], [2], [5], [6], [7]]. Some authors continuing their studies on generalization of continuous maps. Irresolute functions are studied by Crossley and Hilderbrand [3] Sheik John [4] introduced and studied the concepts of strongly w-continuous maps. In this write-up, we initiated the perception of $rg\delta$ -continuous functions.

II. MAIN RESULTS

In this section the new function called $rg\delta$ continuous functions is defined and obtained some results by comparing it with some other continuous functions. Irresolute functions and strongly $rg\delta$ -continuous functions are also discussed in the subsequent sections. Definitions of rw, rwg, sg and gpr-continuous extracted from [8], [9], [10], [11], [12] respectively.

Definition 2.1 A function $e: (R, \psi) \rightarrow (N, \eta)$ is said to be $rg\delta$ -continuous if the inverse image of every closed set in N is $rg\delta$ -closed set in R .

Remark 2.2 [In [8], By Theorem 2.2] Every closed set is $rg\delta$ -closed but not conversely.

Theorem 2.3 If $e: (R, \psi) \rightarrow (N, \eta)$ is continuous then e is $rg\delta$ -continuous.

Proof: Let $G \subset N$, where G is closed. e is continuous

$\Rightarrow e^{-1}(G)$ is closed. By Remark 2.2., $e^{-1}(G)$ is $rg\delta$ -closed.

Hence e is $rg\delta$ -continuous.

Remark 2.4 The converse part fails in Theorem 2.3.

Example 2.5 Let $M = N = \{\eta, \psi, \omega\}$ with $\xi = \{M, \varphi, \{\eta\}, \{\psi\}, \{\eta, \psi\}, \{\psi, \omega\}\}$ and $v = \{N, \varphi, \{\eta\}, \{\omega\}, \{\eta, \omega\}, \{\psi, \omega\}\}$. Let $q: (M, \xi) \rightarrow (N, v)$ be defined by $q(\eta) = \psi$, $q(\psi) = \omega$, $q(\omega) = \eta$. Then f is $rg\delta$ continuous but not continuous as the inverse image of η in N is ω , which is not in M .

Theorem 2.6 Let $h: (P, \sigma) \rightarrow (Q, \eta)$ is $rg\delta$ -continuous if and only if every open in Q is $rg\delta$ -open in P

Proof. Let a function $h: (P, \sigma) \rightarrow (Q, \eta)$ is $rg\delta$ -continuous and let open set H in Q . Then H^c is a closed set in Q . Since h is $rg\delta$ -continuous, $h^{-1}(H^c)$ is $rg\delta$ -closed in P . As $h^{-1}(H^c) = P, h^{-1}(H)$ is $rg\delta$ -open in P .

Converse Part: Let $h^{-1}(H)$ is $rg\delta$ -open in P . Let G be closed set in Q . Then G^c is open in Q . Therefore $h^{-1}(G^c) = P$. Therefore $h^{-1}(G)$ is $rg\delta$ -open. i.e, $h^{-1}(G)$ is closed in X . Thus h is $rg\delta$ -continuous.

Theorem 2.7 If $j: (K, v) \rightarrow (L, \omega)$ is rw-continuous then j is $rg\delta$ -continuous.

Proof. Consider j is rw-continuous, which implies rw-closed set $S \subset L$. $j^{-1}(S)$ is rw-closed in K . Since every rw-closed set is $rg\delta$ -closed set, $j^{-1}(S)$ is $rg\delta$ -closed in K . Hence j is $rg\delta$ -continuous.

Remark 2.8 The reverse part of theorem 2.7 need not true.

Example 2.9 Let $K = \{11, 22, 33, 44, 55\}$ with $v = \{K, \varphi, \{11\}, \{22\}, \{33\}, \{11, 22\}, \{11, 33\}, \{22, 33\}, \{11, 22, 33\}\}$. $L = \{11, 22, 33, 44, 55, 66\}$ $\Psi = \{L, \varphi, \{11\}, \{22\}, \{33\}, \{11, 22\}, \{11, 33\}, \{22, 33\}, \{11, 22, 33\}\}$. Define $j: (K, v) \rightarrow (L, \psi)$ by $j(11) = 44$, $j(22) = 11$, $j(33) = 22$, $j(44) = 44$, $j(55) = 44$. Then j is $rg\delta$ -continuous. Here the closed $\{22, 33\}$ in (L, ψ) is not rw in K .

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Theorem 2.10 If $p : Q \rightarrow R$ is g continuous implies then p is $rg\delta$ -continuous.

Proof. Let $p : Q \rightarrow R$ is g -continuous. Let $K \subset R$. $p^{-1}(K)$ is g -closed in R . Every g -closed set is $rg\delta$ -closed set in R ,

$p^{-1}(K)$ is $rg\delta$ -closed in R . So p is $rg\delta$ -continuous.

Remark 2.11 The contra part fails in Theorem 2.10.

Example 2.12 Let $Q=R=\{i, j, k\}$ with $\tau = \{Q, \phi, \{i\}, \{j\}, \{i, j\}\}$ and $\sigma = \{R, \phi, \{i\}, \{j, k\}\}$. Let $p : Q \rightarrow R$ is identity one. Then p is $rg\delta$ -continuous but not g -continuous

Theorem 2.13 Let $s : (T, \mu) \rightarrow (U, \rho)$ is $rg\delta$ -continuous, then s is rwg -continuous.

Proof. A function $s : (T, \mu) \rightarrow (U, \rho)$ is $rg\delta$ -continuous. Then a K be in U , $s^{-1}(K)$ is in T . Here every $rg\delta$ -closed set is rwg -closed set, $s^{-1}(K)$ is rwg -closed in T . Thus s is rwg -continuous.

Remark 2.14 In Theorem 2.13, the converse part is not satisfied.

Example 2.15 Let $T = \{l, m, n, o\}$ with $\mu = \{T, \phi, \{l\}, \{m\}, \{l, m\}\}$. and $U = \{g, h, i, j\}$ with $\rho = \{T, \phi, \{g\}, \{h\}, \{g, h\}, \{g, h, i\}\}$. Define a function $r : (T, \mu) \rightarrow (U, \rho)$ by $r(l)=g, r(m)=h, r(n)=i, r(o)=j$. Therefore r is rwg -continuous. Hence $p \subset T, \{l, o\} \not\subset T$. Hence $\{l, o\} \not\subset T$ is not $rg\delta$ -closed set in T .

Remark 2.16 sg -continuous and $rg\delta$ -continuous are independent

Example 2.17 Let $T = \{u, v, w, x\}$ with $\zeta = \{T, \phi, \{u\}, \{v\}, \{u, v\}, \{u, v, w\}\}$ and $\Omega = \{u, v, w\}$ with $\xi = \{\Omega, \phi, \{u\}, \{v\}, \{u, v\}\}$. Define a function $o : (T, \zeta) \rightarrow (\Omega, \xi)$ by $o(u) = x, o(v) = v, o(w) = f(x) = u$. Then $o^{-1}(\Omega)$ is $rg\delta$ -closed in T . Thus o is $rg\delta$ -continuous. As the inverse image of (v, w) in ω is u, v is not sg -closed in T . Therefore o is not sg -continuous.

Example 2.18 Let $V = \{v, \psi, \lambda, \kappa\}$ with $\gamma = \{V, \phi, \{v\}, \{\psi\}, \{v, \psi\}, \{v, \psi, \lambda\}\}$ and $W = \{v, \psi, \lambda\}$ with $\beta = \{W, \phi, \{v, \psi\}\}$. Define a function $u : (V, \gamma) \rightarrow (W, \beta)$ by $u(v) = u(\psi) = \alpha$. Thus $u^{-1}(W)$ is sg -closed. Hence u is sg -continuous $u(v) = v, u(w) = u(x) = u$. Then $u^{-1}(W)$ is $rg\delta$ -closed set in T . Thus u is $rg\delta$ -continuous. But u is not $rg\delta$ -continuous, where the closed set λ in W is not $rg\delta$ -closed in V .

Remark 2.19 Implications obtained from 2.1 to 2.18 is given below:

Theorem 2.20 If $d : (C, \psi) \rightarrow (D, \rho)$ is $rg\delta$ -continuous, then d is gpr -continuous.

Proof. Given $d : (C, \psi) \rightarrow (D, \rho)$ is $rg\delta$ -continuous. Let $N \subset D \Rightarrow rg\delta$ -continuous. Then $d^{-1}(N)$ is $rg\delta$ -closed in C . Therefore $d^{-1}(N)$ is gpr -closed in C . Thus d is gpr -continuous.

Remark 2.21 The reverse part is not true in theorem 2.20.

Example 2.22 Let $C = \{\xi, \kappa, \zeta, \omega\}$ with $\psi = \{C, \phi, \{\xi\}, \{\kappa\}, \{\xi, \kappa\}, \{\xi, \kappa, \zeta\}\}$, $D = \{j, k, l\}$, $\rho = \{D, \phi, j\}$. Define $d : (C, \psi) \rightarrow (D, \rho)$ by $d(\xi) = k, d(\kappa) = d(\zeta) = j$. Thus d is gpr -continuous not $rg\delta$ -continuous. Here $d^{-1}(k, l)$ in D is (ξ, ω) in C , not $rg\delta$ -closed in X .

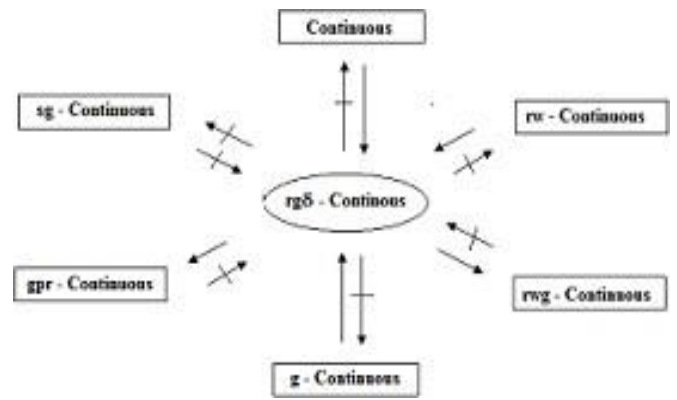


Fig. 1. Implication of $rg\delta$ -continuous.

III. RGA-IRRESOLUTE FUNCTIONS

Definition 3.1 A function $q : (R, \eta) \rightarrow (S, \psi)$ is said to be irresolute function if every $rg\delta$ -closed $q^{-1}(S, \psi)$ is $rg\delta \subset (R, \eta)$.

Theorem 3.2 A map $a : (H, \kappa) \rightarrow (Z, \zeta)$ is $rg\delta$ -irresolute if and only if the $a^{-1}(Z, \zeta)$ -open is $rg\delta$ -open in (H, κ) .

Proof Let $a : (R, \eta) \rightarrow (Z, \zeta)$ be $rg\delta$ -irresolute and W be $rg\delta$ -open in (Z, ζ) . W^c is $rg\delta$ -closed in (Z, ζ) . Here a is $rg\delta$ -irresolute, $a^{-1}(W^c)$ is $rg\delta$ -closed in (H, κ) . Here $a^{-1}(W^c) = (a^{-1}(W))^c$. Hence $a^{-1}(W)$ is $rg\delta$ -open in (Y, κ)

Converse Part: For every $rg\delta$ -open set W in (Z, ζ) assume that $a^{-1}(W)$ is $rg\delta$ -open in (Y, κ) . Let U be a $rg\delta$ -closed set in (Z, ζ) . Now U^c is $rg\delta$ -open in (Z, ζ) , $a^{-1}(U^c)$ is $rg\delta$ -closed in (Y, κ) . Here $a^{-1}(U^c) = (a^{-1}(U))^c$, we have $a^{-1}(U)$ is $rg\delta$ -closed in (Y, κ) . Hence a is $rg\delta$ -irresolute.

Theorem 3.3 A function $z : (A, \psi) \rightarrow (B, \mu)$ is $rg\delta$ -irresolute $\Rightarrow rg\delta$ -continuous.

Proof Let $z : (A, \psi) \rightarrow (B, \mu)$ be $rg\delta$ -irresolute and a closed set $G \in (B, \mu)$. $\Rightarrow G$ is $rg\delta$ (B, μ) . As z is $rg\delta$ -irresolute, $z^{-1}(G)$ is $rg\delta$ -closed in (A, ψ) and therefore z is $rg\delta$ -continuous.



Remark 3.4 g -irresolute and $rg\delta$ -irresolute function are independent.

Example 3.5 Let $K = L = \{m, n, o, p\}$ with $\rho = \{K, \phi, \{m\}, \{n\}, \{m, n\}\}$ and $\omega = \{L, \phi, \{m\}, \{m, n\}\}$. The identity map $w : (K, \rho) \rightarrow (L, \omega)$ is $rg\delta$ -irresolute but it is not g -irresolute. $r^{-1}\{m, p\} \subset (L, \omega)$ is $\{m, p\}$ in (K, ρ) which is $rg\delta$ closed.

Example 3.6 Let $Z = Y = \{\eta, \gamma, v\}$ with $\Gamma = \{Z, \phi, \{\eta\}\}$ and $\epsilon = \{Y, \phi, \{\eta\}, \{\gamma, v\}\}$. Then the function $e : (Z, \Gamma) \rightarrow (Y, \epsilon)$ defined by $e(\eta) = \eta, e(\gamma) = e(v) = v$ is g -irresolute but it is not $rg\delta$ -irresolute function. Since $e^{-1}\{\gamma, v\} \in (Y, \epsilon) \not\subset (Z, \Gamma)$.

IV. STRONGLY $rg\delta$ -CONTINUOUS

Definition 4.1 A function $r : (E, \theta) \rightarrow (F, \zeta)$ is said to be strongly $rg\delta$ -Continuous function if the inverse image of $rg\delta$ -open in (F, ζ) is open in (E, θ) .

Theorem 4.2 A map $i : (V, \omega) \rightarrow (W, \theta)$ is a strongly $rg\delta$ -continuous function iff $i^{-1}(H)$ is closed in (W, θ) .

Proof. Assume $i : (V, \omega) \rightarrow (W, \theta)$ is a strongly $rg\delta$ -continuous function. Let H be $rg\delta$ closed in (W, θ) . Now H^c is a $rg\delta$ -open set in (W, θ) . As i is strongly $rg\delta$ -continuous, $i^{-1}(H^c) = V^{-1}(H)$. Therefore $i^{-1}(H)$ is closed in (W, θ) .

Converse Part: $i^{-1}(H)$ is closed in (W, θ) . Let $G \subset rg\delta$ open (W, θ) , then G^c is a $rg\delta$ -closed in (W, θ) . Since $i^{-1}(G^c) = V^{-1}(G)$ is closed in (V, ω) . i.e., $i^{-1}(G)$ is open in (V, ω) . Thus i is strongly $rg\delta$ -continuous.

Theorem 4.3 A map $n : (G, \alpha) \rightarrow (H, \beta)$ is a strongly $rg\delta$ -continuous then n is continuous.

Proof. Let $n : (G, \alpha) \rightarrow (H, \beta)$ is a strongly $rg\delta$ -continuous Let J be open in (H, β) . As J is $rg\delta$ -open in (H, β) . As n is strongly $rg\delta$ -continuous, $n^{-1}(J)$ is open in (G, α) . Thus n is continuous.

Theorem 4.4 Suppose $v : (C, \beta) \rightarrow (D, \gamma)$ is a strongly $rg\delta$ -continuous then v is strongly g -continuous.

Proof. Let v is strongly $rg\delta$ -continuous. Let $E \subset D$, where E is g -open. Therefore E is $rg\delta$ -open in (D, γ) , v is strongly $rg\delta$ -continuous, As $v^{-1}(E) \subset (C, \beta)$, v is strongly g -continuous.

Example 4.5 Let $Q = \{s, t, u, v\}$ and $R = \{f, x, y, z\}$ $\epsilon = \{R, \phi, \{s\}, \{t\}, \{s, t\}\}$ and $\omega = \{R, \phi, \{f\}, \{x\}, \{f, x\}\}$. The map $t : (Q, \epsilon) \rightarrow (R, \omega)$ defined by $t(s) = f, t(t) = x$, and $t(u) = y, t(v) = z$. t is strongly g -continuous $t^{-1}(y) = u \in (Q, \epsilon)$.

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