

Hybrid Algorithm using the Advantage of Krill Herd Algorithm with Opposition- Based Learning for Dynamic Resource Allocation in Cloud Environment

P Neelima, A. Rama Mohan Reddy

ABSTRACT--- *The cloud computing systems have more consideration due to the growing control for elevated concert computing and data storage. Resource allocation plays a vital role in cloud systems. To overcome the obscurity present in resources allocation system. In this paper, we design and develop a technique for dynamic resource allocation. A Hybridized approach is designed with the help of multi-objective oppositional krill herd optimization algorithm (OKHA). It is a combination of the krill herd algorithm and Opposition-based learning (OBL), OBL is added to get enhanced performance of the krill herd algorithm. The objective of this hybridization is to reduce the cost. In this Hybridized process each task consists of two cost i.e monetary cost and computational cost. Here each task is divided into many subtasks and assigns the respective resources to it. Our proposed multi-objective optimization algorithm will decide allocation of resource for the each subtask in this process. Finally, the testing is passed out, we evaluate our proposed algorithm with PSO, and GA algorithm we verified the performance levels of our proposed Multi-objective optimization algorithm.*

Keywords— *Cloud computing, multi-objective, resources, task, krill herd algorithm, Opposition-based learning*

I. INTRODUCTION

Many service crossways the internet using Cloud Computing technology, which is virtualized and become a milestone in world of networks. Cloud computing mostly targets fault-tolerant, elevated performance, consumption, scalability, high accessibility and easy to use, deal with, provision competence and cost-effective [1]. Since cloud computing has large-scale and complex architecture even though it makes the computing dependable, vibrant and easy, it still faces abundant challenges [2]. The researches on issues apprehend the adoption of cloud computing, being a comparatively recent phenomenon, by both organizations and persons who are in an emerging stage. On the adoption of CC technologies researches conducted so far, quite a small number have approached the problem from the perspective of associations and not from personal user's perspective [3]. Resource allocation is plays a key role in cloud for providing customer needs[4].

From time to time the cost of different resources may vary. Resource allocation deals with providing resources within

deadline for appropriate tasks allocating with proper utilization [6]. In the cloud resource optimization process many challenges has seen into consideration to get the needs of customer in allocation process[7]. To handle resource allocation process, Resource Management System (RMS) is used in resource allocation process, the RMS acquire data about the used and unused resources existing in the system for proper utilization of resources to get profit. Next from the database of the RMS each computing resource will obtain a datum of subtask, and will work until the selected subtasks are completed [8]. A general solution is to shift Virtual Machines (VMs) far from stuffed servers to under-utilized one. To handle the enlarged requests, the process of relocation should consider all potential of operating current available resource, which may cause expenditure of resources might gradually become closely unbalanced between unusual resource dimensions are CPU, disk I/O, memory, bandwidth etc. that causes needless unused of accessible resources and acquire increased cost [9].

Ratan Mishra had given a another view on resource allocation based on the resources like CPU load, memory facility, delay or network load and other resources to customers of load complementary in cloud computing. Soumya Banerjee calculated the objective by examining all the requests in cloud environment to reduce the throughput in scheduling. By customized ant colony framework for expanded service allocation and scheduling mechanism [10]. Green SLA which was designed by Lizhe Wang by considering task execution time and energy-performance. To provide advanced options in power management an approach Dynamic Voltage and Frequency Scaling is proposed by Green SLA that holds up parallel execution and executes number of strategies [11]. A Hybrid algorithm is designed by merge the improvement of Ant Colony Optimization and Cuckoo Search to resolve the job scheduling troubles. Job Scheduling can handle systematic computing and elevated power computing for responding all the combinatorial optimizations problems [12]. The propagation performance of cuckoos and the uniqueness of Levy flights of flies initiate the new behavior, and then trail its success. By investigating other trendy optimization algorithms we will estimate the planned investigate plan and converse our findings and their presumption for a diversity of optimization tribulations [13].

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HYBRID ALGORITHM USING THE ADVANTAGE OF KRILL HERD ALGORITHM WITH OPPOSITION-BASED LEARNING FOR DYNAMIC RESOURCE ALLOCATION IN CLOUD ENVIRONMENT

A multi-objective optimization algorithm is designed for resource allocation in cloud computing will be done in dynamically. The main motive of this algorithm is that, dynamically resources need to be allocated based on the principle of tasks sub division. By consider the monetary cost and computational cost we design the multi-objective fitness. Here, an hybridized is applied between the krill herd algorithm with oppositional-based learning (OBL), by optimizing the cost function here an improvement is seen compare to previous findings. Firstly the OKHA algorithm is will generate the initial solution based on the number of subtask; secondly it calculates the multi-objective fitness for each krill of the initial solution. After that, we generate the opposite solution of the each task. Then, KHA algorithm updates the initial solution. The remaining paper is ordered as follows: in Section 2 brief reviews of several literature works in resource allocation. In Section 3 the proposed algorithm for dynamic resource allocation is discussed. Section 4 enclosed with proposed algorithm. Section 5 will presents the performance of different algorithms with tabbed values and section 6 will be conclusion of this paper.

II. RELATED WORK

Fatma A.Omara *et al.* [14] have developed an approach for resource allocation problem, which mainly focused two main modules, (1) Virtual Design Advisor (VDA) and (2) calibration process. In the first module, the VDA was used to estimate the cost of performance in the database management system (DBMS). To enhance and minimizing the cost function a Greedy Particle Swarm Optimization (GPSO) search algorithm was developed.

Siva Theja Maguluri [15] have elucidate important traffic resource allocation in cloud computing, which mainly used to study stochastic model of cloud computing. To overcome the problems in load balancing and scheduling a hybridized process is evolved with the combination of join-the-shortest-queue routing and power-of-two-choices routing algorithm. The main motivation is purely implemented on basis of queue length and it resembles in optimality in the heavy traffic limit. Rather than, S. Chandrasekhar and Paxar Rajnikant B [20] have explained about dynamic resource allocation in cloud computing based on priority.

There were presented many resources to satisfy customer need in the dynamic resource allocation. These recourses were finished by service level agreement (SLA) and with the aid of parallel processing.

Either-or, Sagar S. Brahmshatriya and Jignesh Prajapati [23] have explained and provided evaluation on techniques of resource allocation in cloud computing, which mainly focused in to two modules (1) virtualization and (2) automation. Initial module is facilitating the process of virtualization to maximize the profit for cloud providers and second module, was used to diminish the cost for cloud consumers. Moreover, Saraswathi AT *et al.* [18] have explained dynamic resource allocation in cloud computing, virtual machine (VM) technology is mainly concentrated. The main principle of Virtual machine works as with low priority jobs as well as with high priority jobs. Rather than, Dr.R.Sridaran *et al.* [19] have explained survey on resource allocation in cloud computing, which mainly used by Resource allocation strategy (RAS). RAS is developed to

carry out the objective of minimizing the cost in cloud by using the optimum resource algorithm. An algorithm was proposed for finding the cost in cloud. Moreover, Pavithra.B and Ranjana.R [21] have provided a detailed view on resource allocation in cloud computing by conducting a survey on virtual machines. The main objective of VM was to reduce the power consumption in large cloud data centers and with more profit.

To maximize the profit for cloud service provider B.Rajasekar and S.K.Manigandan [22] have described a powerful resource allocation in cloud computing. There is a problem is a raised by taking the resources as rental. so many limitations have seen while the users are considering the concept of Quality with his rented resources. Either or Fredy Juarez *et al.* [17] have explained Dynamic energy for Task based application in cloud computing based on parrellsim, To minimize the energy consumption a task based applications is executed in distributed computing platforms. This mainly focused virtualization technology (VT). VT was used for resource allocation by considering low level nodes addition as well as removal of nodes under allocating process.

III PROPOSED DYNAMIC RESOURCE ALLOCATION USING KRILL HERD ALGORITHM

The main intention of this paper is develop a technique for dynamic resource allocation in distributed computing using Krill Herd Algorithm (KHA). Both monetary cost and computational cost is taken into consideration for scheduling tasks in cloud. A task is divided into various tasks and provides the selected best one as a available resource to the task to reduce the total cost of the task. The proposed KHA is used to allocate the task in to equivalent cloud resources by taking both monetary and computational tasks as input. Moreover, this KHA algorithm helps to decrease the cost of every subtask.

3.1 Multi-objective function

To achieve the optimal resource allocation, a multi objective function is developed. The multi objective function is defined as the combination of monetary cost and computational cost.

Monetary cost:

The cost that is allocated by the service provider to the client, to fulfill client's task and to develop the resources. The monetary cost differs from one provider to another for the execution of same task.

Computational cost:

It is decided by service provider depended upon the complexity of the task assigned by the user. This cost is varies at different times and computational complexities contain the execution time, memory space.

The proposed multi objective based resource allocation using oppositional krill herd algorithm step by step process is explained below.

Step 1: Solution encoding

In cloud computing, an one of the important theme is to indicate a solution for resource allocation. At first we randomly generate the Q_i number of solution. The solution consists of subtask and resources and the solution in the form of matrix. The solution matrix picks the resource for every subtask and the matrixes are efficient through KHA algorithm up to K number of iteration after the calculation of fitness. Generate Q number of initialization matrix with size of $N \times M$ where N represents dimension of the matrix (number of resources) and M represents the amount of cuckoo particles (number of subtasks). The initial solution format is given in table 1 and updation matrix is given in table 2.

$Y_1 =$

T_i	RS_1	RS_2	RS_3	RS_4	RS_5	RS_6	RS_7
T_{S1}	0	0	0	1	0	0	0
T_{S2}	1	0	0	0	0	0	0
T_{S3}	0	0	0	0	1	0	0
T_{S4}	1	0	0	0	0	0	0
T_{S5}	0	1	0	0	0	0	0

Table 1: Example of initial solution

Step 2: Oppositional solution

According to iTizhoosh in 2005 [24] opposition based learning (OBL) is implemented as, to get the updated krill position we are considering both the current and opposite krill position. The opposite krill solution has a better opportunity to get the details and update the current krill position based on global optimal solution. The opposite

krill's positions OY_i are completely defined by components of Y_i .

$$OY_i = [oy_i^1, \dots, oy_i^d]$$

where, $oy_i^d = L^d + U^d - y_i^d$ with $oy_i^d \in [L^d, U^d]$ is the position of i^{th} opposite agent OY_i in the d^{th}

dimension of opposite population.

Step 3: Fitness calculation

After that we calculate the fitness function of each solution. To calculate fitness function a multi-objective function is designed. In each task T we calculate the fitness function.

The fitness of the task T is intended through KHA notion. The total cost of the task T is derived from the computational cost (objective 1; $F(O_1)$) and monetary cost (objective 2; $F(O_2)$) of the number of all subtasks T_{S_m} . Here, at first we calculate the computation cost $F(O_1)$ and further calculate the monetary cost $F(O_2)$. By the summation of computational cost of the all subtask by means of corresponding resources, the objective 1 is interconnected to the computational cost of the task T that is calculated. The objective 2 is interrelated with the monetary cost, and calculated by the summation of computational cost of the

every subtask with respective resources. To estimate the objective function 1 and 2 of the task T and to calculate it, we use the following equations 1 and 2 correspondingly.

$$F(O_1(T)) = \sum_{m=1}^M CC_m \tag{1}$$

$$F(O_2(T)) = \sum_{m=1}^M MC_m \tag{2}$$

$$F(T) = F(O_1(T)) + F(O_2(T)) \tag{3}$$

Step 4: Krill Herd Algorithm based solution updation

Krill Herd Algorithm (KHA) is new optimization Algorithm that is developed for resolving optimization tribulations from optimization process. The main motivation for developing this krill optimization algorithm is, made-up to be an arrangement of the smallest amount distances of the location of the food and the maximum density of the herd. The KHA track the exploration orders that improve the objective function value and duplicate the implementation of the three movements. The KH algorithm is mainly follows the Lagrangian model for effective search which is shown in below equation (5);

$$\frac{dv_p}{dt} = X^{new}_p + X^{new}_F + X^{new}_{D_p} \tag{4}$$

Where X^{new}_p , is the motion bring by other krill individuals, X^{new}_F , is the foraging motion and $X^{new}_{D_p}$ physical distribution of the krill individuals correspondingly.

❖ Calculation of induction motion

The movement of the krill individual X^{new} is shown in equation (5):

$$X^{new}_p = \phi X^{max} + v X^{old} \tag{5}$$

$$\phi_p = \phi_p^{local} + \phi_p^{target} \tag{6}$$

X^{max}_P is the maximum induced speed, v_w is the

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inertia weight, X_P^{old} is the motion, \square_{local} is the local effect obtainable by neighbors and ϕ_{best} is the best krill individual's target effect.

❖ Calculation of Foraging Action

The second progress of KH algorithm is Foraging action. It is derivative from two key factors. Firstly the current food location and earlier food location. The foraging velocity might be articulated for the pth krill individual by

$$X_F^{new} = 0.02 \times 2 \times |1 - \frac{v_F}{\sum_{k=1}^n v_k}| \times X_F^{old} + \gamma \times X_F^{old} \tag{7}$$

where v_F is the inertia weight of the foraging motion, X_F^{new} and X_F^{old} are the foraging motions of the new and the old pth krill, correspondingly.

❖ Calculation of Physical diffusion

In this KH approach a physical diffusion is introduced.

$$X_{Dp}^{new} = \alpha \times X_D^{max} \tag{8}$$

❖ Position updation:

In this procedure, derived from induction motion, foraging motion and physical diffusion motion, the individual Krill modifies its present positions and shifts to improved positions. The updated position of the pth krill individual may be expressed as;

$$V_p^{new} = v_p^{new} + (X_p^{new} + X_{Fp}^{new} + X_{Dp}^{new}) \times Pc \sum_{q=1}^{n_d} (V_q - L_q) \tag{9}$$

where n is the total number of variables, V_q and L_q are the upper and the lower limits of the qth variables.

After the updation of each dimension of every data point of the solution matrix, this named as updation matrix of the KHA algorithm which is represented in the following table 2.

	R ₁	R ₂	R ₃	R ₄	R ₅	R ₆	R ₇
Ts ₁	1	0	0	0	0	0	0
Ts ₂	0	1	0	0	0	0	0
Ts ₃	0	0	0	1	0	0	0
Ts ₄	0	1	0	0	0	0	0
Ts ₅	0	0	0	1	0	0	0

Table 2: Updation table of KHA algorithm

After the conversion of the initialization matrix in to updation matrix, the OKHA algorithm starts its process by consider those updation matrixes as input.

Step 5: Termination criteria

If maximum value number of iterations is achieved then the best solution is find. After finding the best solution the algorithm will discontinues.. Once the best fitness is achieve by means of KHA algorithm, selected solution is allocated for task. Pseudo code of proposed methodology is given below:

IV PROPOSED ALGORITHM

Input: M number of subtasks, N Number of resources, monetary cost M^C , computational cost

$$C^C$$

Output: Minimum cost of resource allocation for each subtask.

Initialize the Parameters:

N = Number of resources

M = Number of subtasks

M^C = Monetary cost

C^C = Computational cost

k = Iteration counter

K = maximum iteration counter

f_{t^k} = fitness of mth subtask at kth iteration

C_{mn}^C = communication cost of mth task

with nth resource

M_{mn}^C = monetary cost of mth task with nth resource

Step 1: Start

Step2: Randomly generate the krill individual Evaluate the fitness (FF_i) function and find out best and worst solution

Set cycle to 1

Step 3: While (stopping condition is not met) do Store the pre-specified number of best krill **For** each krill Calculate the movement influenced by other krill individual

using (5) Calculate foraging action using (7)

Step 4: Calculate physical diffusion using(8) update krill position using (9)evaluate the objective function value and update the krill individual end for replace the worst krill with the best krill end while

Step 5: Best solution

V PERFORMANCE EVALUATION OF PROPOSED ALGORITHM & RESULTS

The primary purpose of this research is to design and develop a method for dynamic resource allocation through the help of multi-objective optimization algorithm. Our main objective is to allocate the resource with minimum computational costs. Here, the performance evaluation of the proposed multi objective optimization algorithm is prepared by compared with the particle swarm optimization and particle swarm optimization genetic algorithm algorithm are shown in table 3. The parameters used in the krill herd algorithm are shown in table 4

Number of resources	D1 dataset			D2 dataset		
	Proposed	PSO	GA	Proposed	PSO	GA
25	22.50	27.99	27.63	20.52	25.10	25.4
50	22.0	27.5	27.00	21.19	24.21	25.11

Table 3: Represents the average performance of the three algorithms

Pop_size	maxGen	ω_n	χ_p^{\max}	ϵ	rand	v_{w_r}	χ_D^{new}
2D (Dimension)	100	0.1	0.01ms ⁻¹	0.1	0.1	0.02ms ⁻¹	0.002ms ⁻¹

Table 4: Parameter used in the KHA

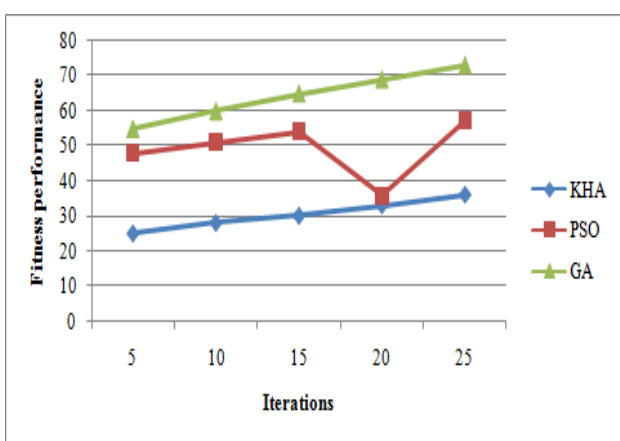


Figure 1: Performance of fitness function for KHA

VI CONCLUSION

In this paper, an approach of multi-objective optimization algorithm is designed for dynamic resource allocation in cloud computing. Firstly, the OKHA algorithm will produce a solution matrix based on the amount of subtasks and then it computed the fitness for each and every subtask based on the evaluation of costs (monetary and computational costs). After that, the solution is updated based on the oppositional krill herd algorithm. Here, we hybridization takes place between the krill herd algorithm and oppositional –based

learning (OBL), OBL is used to optimize the cost function which will resembles in improving the performance of the previous krill herd algorithm. The updated solution matrix is assigned to OKHA algorithm. The process will be iterated up to K times. The experimentation is conceded out, we compared our proposed algorithm with GA and PSO algorithm, and we proved efficiency of our proposed multi-objective optimization algorithm.

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