

# Image Segmentation using a Fuzzy Roughness Measure



Sheeja T. K, Sunny Kuriakose A.

**Abstract:** Measures of uncertainty are highly useful for determining the information content of a system. In this paper, new measures of information on fuzzy approximation spaces are introduced based on divergence measures of fuzzy sets. The proposed fuzzy rough uncertainty measure is used to develop an algorithm for histogram based foreground background segmentation of a grey level image and it is experimented with twelve standard test images. It is observed that the overlapping of the foreground background pixels in the images segmented using the proposed method is lesser than those produced by OTSU and FCM methods. The segmented images are compared using their root mean square error values.

**Index Terms:** Rough set, Fuzzy rough set, Uncertainty measure, Image segmentation.

## I. INTRODUCTION

Image segmentation refers to partitioning of an image into different non-intersecting homogeneous regions. It is a basic process in image analysis. There are many different methodologies that use gray level histogram, spatial details, mathematical morphology, fuzzy set theoretic approaches, neural networks etc. which are successfully applied in image segmentation [3], [8], [7]. Gray level thresholding is a simple and popular method used for the binary segmentation of a gray level image. Some thresholding techniques are described in [5], [18]. OTSU and FCM methods are two classic methods used for image segmentation which are very popular in the image processing research domain [1], [14]. In OTSU method, the threshold is obtained by maximizing the inter-class intensity variance, whereas in FCM method the threshold is determined by optimizing an objective function defined using a measure of similarity between the pixels and the cluster centres.

The theory of rough sets was introduced by Z. Pawlak in early 1980's [15]. It has become a potential tool to manage the uncertainty in data caused by incomplete information. Rough set theory along with its generalized versions have found successful applications in machine learning, decision analysis, artificial intelligence, expert systems, inductive reasoning etc. Information theory, introduced by C. E.

Shannon [19], studies the transmission, processing, extraction, and utilization of information. Uncertainty measures play a vital role in information theory as means for quantifying the capacity of a system to process information.

Many attempts are there in the literature, to define uncertainty measures in the context of rough sets and fuzzy rough sets [10], [20], [23]. Studies on the applications of rough set concepts to image processing are given in [6]. In this paper, new uncertainty measures on fuzzy approximation spaces are defined based on fuzzy divergence measures. Divergence measures provide an indication of the extent of difference between two fuzzy sets [13]. It is shown that these new measures are generalizations of some of the existing uncertainty measures on crisp and fuzzy approximation spaces. Further, a histogram based image thresholding algorithm using the fuzzy roughness measure is presented and experimented with different images. The segmented images of twelve standard test images namely, *baboon*, *barbara*, *boat*, *bridge*, *cameraman*, *house*, *lena*, *mountain*, *peppers*, *rice*, *sailboat* and *zelda* are compared with those of OTSU method and FCM method. It is observed that the overlapping of the foreground background pixels in the images segmented using the proposed method is lesser than those produced by the OTSU and FCM methods. Further, the proposed algorithm produces images having the least root mean square error values in ten out of twelve cases. The remaining part of the paper is organized as follows: some basic concepts related to this paper are recalled in section 2, section 3 presents the new fuzzy rough uncertainty measures, section 4 describes an application of the proposed measure to image segmentation and conclusion is given in section 5.

## II. BASIC CONCEPTS

Consider a non-empty finite set of objects denoted by  $U$ . Let  $\Theta$  be a fuzzy equivalence relation on  $U$ .

**Definition 2.1.** [9] The fuzzy equivalence classes of  $\Theta$  are defined  $\forall u \in U$  as,  $\mu_{[u]_{\Theta}}(v) = \Theta(u, v)$ ,  $\forall v \in U$ .

**Definition 2.2.** [22] The fuzzy cardinality of a fuzzy subset  $X$  of  $U$  is given by,  $|X| = \sum_{u \in U} X(u)$

**Definition 2.3.** [4] A weak fuzzy partition on  $U$  is a collection  $\{A_1, A_2, \dots, A_k\}$  of fuzzy sets on  $U$  such that  $\inf_u (\max_i A_i(u) > 0$  and  $\sup_u (\min_j (A_i(u), A_j(u)) < 1, \forall i, j$ .

**Definition 2.4.** [13] A function  $\delta : \mathcal{F}(U) \times \mathcal{F}(U) \rightarrow R$  is said to be a divergence measure iff  $\forall X, Y, Z \in \mathcal{F}(U)$ ,

- i.  $\delta(X, X) = 0$
- ii.  $\delta(X, Y) = \delta(Y, X)$
- iii.  $\max(\delta(X \cup Z, Y \cup Z), \delta(X \cap Z, Y \cap Z)) \leq \delta(X, Y)$

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where,  $\mathcal{F}(U)$  is the collection of all fuzzy sets on  $U$ .

**Proposition 2.5.** [13] For the fuzzy subsets  $X, Y, Z, W$  of  $U$  such that  $X \subseteq Y \subseteq Z \subseteq W$ ,  $\delta(Y, Z) \leq \delta(X, W)$

**Definition 2.6.** [15] Let  $\theta$  be a crisp equivalence relation on  $U$ . Then, the lower approximation and the upper approximation of  $X \subseteq U$  with respect to  $\theta$  are respectively defined as

$$\underline{\theta}(X) = \{u \in U : [u]_{\theta} \subseteq X\} \text{ and } \overline{\theta}(X) = \{u \in U : [u]_{\theta} \cap X \neq \Phi\}.$$

**Definition 2.7.** [16] The  $\theta$  - roughness of  $X \subseteq U$  is given by

$$\rho_{\theta}(X) = 1 - \frac{\theta(X)}{\overline{\theta}(X)}$$

**Definition 2.8.** [20] Consider  $U/\theta = \{\theta_1, \theta_2, \dots, \theta_k\}$ . An information measure of  $(U, \theta)$  is given by

$$G(\theta) = - \sum_{i=1}^k \frac{|\theta_i|}{|U|} \log_2 \frac{|\theta_i|}{|U|}.$$

**Definition 2.9.** [4] The fuzzy rough lower and upper approximations of a fuzzy set  $X$  on  $U$  are given by

$$\mu_{\underline{\theta}(X)}(u) = \inf_{v \in U} \max(1 - \theta(u, v), \mu_X(v))$$

$$\mu_{\overline{\theta}(X)}(u) = \sup_{v \in U} \min(\theta(u, v), \mu_X(v))$$

respectively.

There are several intensive studies on the theory and applications of fuzzy rough sets [12], [17], [21]. A survey of the various approaches to fuzzy rough sets was conducted by L. Deer et al [2].

**Definition 2.10.** [11] Let  $U = \{u_1, u_2, \dots, u_n\}$ . The entropy of the fuzzy approximation space  $(U, \Theta)$  is given by,

$$F(\Theta) = - \sum_{i=1}^n \frac{1}{|U|} \log_2 \frac{|[ui]_{\Theta}|}{|U|}$$

### III. INFORMATION MEASURES ON FUZZY APPROXIMATION SPACES

Let  $U = \{u_1, u_2, \dots, u_n\}$ . Let  $[ui]_{\Theta}$  represents a fuzzy equivalence class of  $(U, \Theta)$ . That is,  $[ui]_{\Theta}: U \rightarrow [0,1]$ ,  $\mu_{[ui]_{\Theta}}(v) = \Theta(u_i, v)$ ,  $\forall u_j \in U$ . Also, let  $\widehat{U}$  be the fuzzy set  $\widehat{U}: U \rightarrow [0,1]$ ,  $\widehat{U}(u_i) = 1, \forall u_i \in U$  and  $\widehat{\Phi}$  be the fuzzy set  $\widehat{\Phi}: U \rightarrow [0,1]$ ,  $\widehat{\Phi}(u_i) = 0, \forall u_i \in U$ . Let  $\delta(X, Y)$  be a divergence measure on  $\mathcal{F}(U) \times \mathcal{F}(U)$ . For notational convenience, we assume that  $\log_2(0) = 0$ .

**Definition 3.1.** For the fuzzy approximation space  $(U, \Theta)$ , the  $\delta$  -information entropy is defined as

$$E_{\delta}(\Theta) = - \frac{1}{|U|} \sum_{i=1}^n \log_2 \left( 1 - \frac{\delta(\widehat{U}, [ui]_{\Theta})}{\delta(\widehat{U}, \widehat{\Phi})} \right) \quad (1)$$

**Proposition 3.2** On a fuzzy approximation space  $(U, \Theta)$ , if  $\Theta(u_i, u_j) = 1, \forall u_i, u_j \in U$ , then  $E_{\delta}(\Theta) = 0$ .

*Proof:*

$$\Theta(u_i, u_j) = 1, \forall u_i, u_j \in U \Rightarrow [ui]_{\Theta} = \widehat{U}, \forall u_i \in U$$

$$\Rightarrow \delta(\widehat{U}, [ui]_{\Theta}) = \delta(\widehat{U}, \widehat{U}) = 0, \forall u_i \in U$$

$$\Rightarrow \log_2 \left( 1 - \frac{\delta(\widehat{U}, [ui]_{\Theta})}{\delta(\widehat{U}, \widehat{\Phi})} \right) = \log_2 \left( 1 - \frac{0}{\delta(\widehat{U}, \widehat{\Phi})} \right)$$

$$= \log_2 1 = 0, \forall u_i \in U$$

Hence, from equation (1),  $E_{\delta}(\Theta) = 0$ .

Now, we will show that the information measure on a crisp approximation space defined by Wiermann [20] is a special case of the proposed  $\delta$ -information entropy measure.

**Theorem 3.3** Consider a crisp approximation space  $(U, \theta)$ . Then,  $E_{\delta}(\theta) = G(\theta)$  if  $\delta(X, Y) = \sum_{j=1}^n |X(u_j) - Y(u_j)|$ .

*Proof:*

Let  $U/\theta = \{\theta_1, \theta_2, \dots, \theta_k\}$ . Then, each  $u \in U$  is an element of exactly one equivalence class. We have,

$$\theta(u_i, u_j) = \begin{cases} 1, & \text{if } u_j \in [ui]_{\theta} \\ 0, & \text{otherwise} \end{cases}$$

$$\begin{aligned} \text{Hence, } \delta(\widehat{U}, [ui]_{\theta}) &= \sum_{j=1}^n |\widehat{U}(u_j) - [ui]_{\theta}(u_j)| \\ &= \sum_{j=1}^n |1 - \theta(u_i, u_j)| = \sum_{u_j \notin [ui]_{\theta}} 1 \\ &= |([ui]_{\theta})^c| = |U| - |[ui]_{\theta}| \end{aligned}$$

$$\text{Also, } \delta(\widehat{U}, \widehat{\Phi}) = \sum_{j=1}^n |\widehat{U}(u_j) - \widehat{\Phi}(u_j)| = \sum_{j=1}^n |1 - 0| = |U|$$

$$\begin{aligned} \text{Therefore, } E_{\delta}(\theta) &= - \frac{1}{|U|} \sum_{i=1}^n \log_2 \left( 1 - \frac{\delta(\widehat{U}, [ui]_{\theta})}{\delta(\widehat{U}, \widehat{\Phi})} \right) \\ &= - \frac{1}{|U|} \sum_{i=1}^n \log_2 \left( 1 - \frac{|U| - |[ui]_{\theta}|}{|U|} \right) \\ &= - \sum_{i=1}^n \frac{1}{|U|} \log_2 \left( \frac{|[ui]_{\theta}|}{|U|} \right) \end{aligned}$$

Let  $[ui]_{\theta} = \theta_j$ . Then, in the above sum, each term  $\frac{1}{|U|} \log_2 \left( \frac{|[ui]_{\theta}|}{|U|} \right)$  is repeated  $\theta_j$  times. Hence, it follows that,

$$E_{\delta}(\theta) = - \sum_{i=1}^k \frac{|\theta_j|}{|U|} \log_2 \left( \frac{|\theta_j|}{|U|} \right) = G(\theta).$$

The fact that the fuzzy rough entropy proposed by J. S. Mi et al. [11] is a special case of the proposed  $\delta$ -information entropy measure is asserted in the next theorem.

**Theorem 3.4** On a fuzzy approximation space  $(U, \Theta)$ ,  $E_{\delta}(\Theta) = F(\Theta)$ , for  $\delta(X, Y) = \sum_{j=1}^n |X(u_j) - Y(u_j)|$

*Proof:*

$$\begin{aligned} E_{\delta}(\Theta) &= - \frac{1}{|U|} \sum_{i=1}^n \log_2 \left( 1 - \frac{\delta(\widehat{U}, [ui]_{\Theta})}{\delta(\widehat{U}, \widehat{\Phi})} \right) \\ &= - \frac{1}{|U|} \sum_{i=1}^n \log_2 \left( 1 - \frac{\sum_{j=1}^n |\widehat{U}(u_j) - [ui]_{\Theta}(u_j)|}{\sum_{j=1}^n |\widehat{U}(u_j) - \widehat{\Phi}(u_j)|} \right) \\ &= - \frac{1}{|U|} \sum_{i=1}^n \log_2 \left( 1 - \frac{\sum_{j=1}^n |1 - \Theta(u_i, u_j)|}{\sum_{j=1}^n |1 - 0|} \right) \\ &= - \frac{1}{|U|} \sum_{i=1}^n \log_2 \left( 1 - \frac{|U| - \sum_{j=1}^n \Theta(u_i, u_j)}{|U|} \right) \\ &= - \frac{1}{|U|} \sum_{i=1}^n \log_2 \left( \frac{\sum_{j=1}^n \Theta(u_i, u_j)}{|U|} \right) \\ &= - \frac{1}{|U|} \sum_{i=1}^n \log_2 \left( \frac{|[ui]_{\Theta}|}{|U|} \right) = F(\Theta) \end{aligned}$$

The monotonic property of the  $\delta$ -information entropy measure is presented in the theorem given below.

**Theorem 3.5** If  $\Theta_1$  and  $\Theta_2$  are fuzzy equivalence relations on  $U$  and  $\Theta_1 \subseteq \Theta_2$ , then  $E_{\delta}(\Theta_1) \geq E_{\delta}(\Theta_2)$ .

*Proof:*

$$\Theta_1 \subseteq \Theta_2 \Rightarrow \Theta_1(u_i, u_j) \leq \Theta_2(u_i, u_j), \forall u_i, u_j \in U$$

$$\Rightarrow [ui]_{\Theta_1}(u_j) \leq [ui]_{\Theta_2}(u_j), \forall u_i, u_j \in U$$

$$\Rightarrow [ui]_{\Theta_1} \subseteq [ui]_{\Theta_2} \subseteq \widehat{U}, \forall u_i \in U$$

$$\Rightarrow \delta(\widehat{U}, [ui]_{\Theta_1}) \geq \delta(\widehat{U}, [ui]_{\Theta_2}), \forall u_i \in U$$

$$\Rightarrow \frac{\delta(\widehat{U}, [ui]_{\Theta_1})}{\delta(\widehat{U}, \widehat{\Phi})} \geq \frac{\delta(\widehat{U}, [ui]_{\Theta_2})}{\delta(\widehat{U}, \widehat{\Phi})}$$

$$\Rightarrow \log_2 \left( 1 - \frac{\delta(\widehat{U}, [ui]_{\Theta_1})}{\delta(\widehat{U}, \widehat{\Phi})} \right) \leq \log_2 \left( 1 - \frac{\delta(\widehat{U}, [ui]_{\Theta_2})}{\delta(\widehat{U}, \widehat{\Phi})} \right)$$

$$\Rightarrow E_{\delta}(\Theta_1) \geq E_{\delta}(\Theta_2)$$

**Definition 3.6** The joint  $\delta$ -information entropy of the fuzzy equivalence relations  $\Theta_1$  and  $\Theta_2$  on  $U$  is defined as

$$E_{\delta}(\Theta_1; \Theta_2) = - \frac{1}{|U|} \sum_{i=1}^n \log_2 \left( 1 - \frac{\delta(\widehat{U}, [ui]_{\Theta_1} \cap [ui]_{\Theta_2})}{\delta(\widehat{U}, \widehat{\Phi})} \right) \quad (2)$$

**Definition 3.7** The conditional  $\delta$ -information entropy of the fuzzy equivalence relation  $\Theta_1$  given  $\Theta_2$  is defined to be

$$E_{\delta}(\Theta_1 | \Theta_2) = - \frac{1}{|U|} \sum_{i=1}^n \log_2 \left( \frac{\delta(\widehat{U}, \widehat{\Phi}) - \delta(\widehat{U}, [ui]_{\Theta_1} \cap [ui]_{\Theta_2})}{\delta(\widehat{U}, \widehat{\Phi}) - \delta(\widehat{U}, [ui]_{\Theta_2})} \right) \quad (3)$$

**Theorem 3.8** For two fuzzy equivalence relations  $\Theta_1$  and  $\Theta_2$  on  $U$ ,  $E_{\delta}(\Theta_1 | \Theta_2) = E_{\delta}(\Theta_1; \Theta_2) - E_{\delta}(\Theta_2)$

*Proof:*



We have,  $E_\delta(\Theta_1: \Theta_2) - E_\delta(\Theta_2) =$   

$$-\frac{1}{|U|} \sum_{i=1}^n \log_2 \left( 1 - \frac{\delta(\bar{U}, [ui]_{\Theta_1} \cap [ui]_{\Theta_2})}{\delta(\bar{U}, \bar{\theta})} \right) -$$
  

$$-\frac{1}{|U|} \sum_{i=1}^n \log_2 \left( 1 - \frac{\delta(\bar{U}, [ui]_{\Theta_2})}{\delta(\bar{U}, \bar{\theta})} \right) =$$
  

$$-\frac{1}{|U|} \sum_{i=1}^n \log_2 \frac{1 - \frac{\delta(\bar{U}, [ui]_{\Theta_1} \cap [ui]_{\Theta_2})}{\delta(\bar{U}, \bar{\theta})}}{1 - \frac{\delta(\bar{U}, [ui]_{\Theta_2})}{\delta(\bar{U}, \bar{\theta})}}$$
  

$$= -\frac{1}{|U|} \sum_{i=1}^n \log_2 \left( \frac{\delta(\bar{U}, \bar{\theta}) - \delta(\bar{U}, [ui]_{\Theta_1} \cap [ui]_{\Theta_2})}{\delta(\bar{U}, \bar{\theta}) - \delta(\bar{U}, [ui]_{\Theta_2})} \right) = E_\delta(\Theta_1 | \Theta_2)$$

**Definition 3.9** Let  $\Theta_1$  and  $\Theta_2$  be fuzzy equivalence relations on  $U$ . Then the  $\delta$ -mutual information of  $\Theta_1$  and  $\Theta_2$  is defined as  $I_\delta(\Theta_1: \Theta_2) =$

$$-\frac{1}{|U|} \sum_{i=1}^n \log_2 \left( \frac{(\delta(\bar{U}, \bar{\theta}) - \delta(\bar{U}, [ui]_{\Theta_1})) (\delta(\bar{U}, \bar{\theta}) - \delta(\bar{U}, [ui]_{\Theta_2}))}{\delta(\bar{U}, \bar{\theta}) (\delta(\bar{U}, \bar{\theta}) - \delta(\bar{U}, [ui]_{\Theta_1} \cap [ui]_{\Theta_2}))} \right) \quad (4)$$

**Theorem 3.10** If  $\Theta_1$  and  $\Theta_2$  are fuzzy equivalence relations on  $U$ , then  $I_\delta(\Theta_1: \Theta_2) = E_\delta(\Theta_1) - E_\delta(\Theta_1 | \Theta_2)$

*Proof:*

We have,  $E_\delta(\Theta_1) - E_\delta(\Theta_1 | \Theta_2) =$   

$$-\frac{1}{|U|} \sum_{i=1}^n \log_2 \left( 1 - \frac{\delta(\bar{U}, [ui]_{\Theta_1})}{\delta(\bar{U}, \bar{\theta})} \right) -$$
  

$$-\frac{1}{|U|} \sum_{i=1}^n \log_2 \left( \frac{\delta(\bar{U}, \bar{\theta}) - \delta(\bar{U}, [ui]_{\Theta_1} \cap [ui]_{\Theta_2})}{\delta(\bar{U}, \bar{\theta}) - \delta(\bar{U}, [ui]_{\Theta_2})} \right)$$
  

$$= -\frac{1}{|U|} \sum_{i=1}^n \log_2 \left( \frac{\frac{\delta(\bar{U}, \bar{\theta}) - \delta(\bar{U}, [ui]_{\Theta_1})}{\delta(\bar{U}, \bar{\theta})}}{\frac{\delta(\bar{U}, \bar{\theta}) - \delta(\bar{U}, [ui]_{\Theta_1} \cap [ui]_{\Theta_2})}{\delta(\bar{U}, \bar{\theta}) - \delta(\bar{U}, [ui]_{\Theta_2})}} \right)$$
  

$$= -\frac{1}{|U|} \sum_{i=1}^n \log_2 \left( \frac{(\delta(\bar{U}, \bar{\theta}) - \delta(\bar{U}, [ui]_{\Theta_1})) (\delta(\bar{U}, \bar{\theta}) - \delta(\bar{U}, [ui]_{\Theta_2}))}{\delta(\bar{U}, \bar{\theta}) (\delta(\bar{U}, \bar{\theta}) - \delta(\bar{U}, [ui]_{\Theta_1} \cap [ui]_{\Theta_2}))} \right)$$
  

$$= I_\delta(\Theta_1: \Theta_2)$$

In the following, we propose a fuzzy roughness measure of a fuzzy set using the divergence measure  $\delta$  and prove that it generalizes Pawlak's roughness measure [16].

**Definition 3.11** Let  $(U, \Theta)$  be a fuzzy approximation space. Then the  $\delta$ -fuzzy roughness measure of a fuzzy set  $X \neq \emptyset$  on  $U$  is defined as

$$E_\delta^\Theta(X) = \frac{\delta(\bar{\Theta}(X), \underline{\Theta}(X))}{\delta(\bar{\Theta}(X), \bar{\theta})} \quad (5)$$

**Theorem 3.12** The  $\delta$ -fuzzy roughness measure of a crisp set  $X$  on a crisp approximation space  $(U, \theta)$  is the same as the roughness of  $X$  with respect to  $\theta$ , when  $\delta(X, Y) = \sum_{j=1}^n |X(u_j) - Y(u_j)|$

*Proof:*

We have,  $\theta(u_i, u_j) = \begin{cases} 1, & \text{if } u_j \in [ui]_\theta \\ 0, & \text{otherwise} \end{cases}$

Hence,  $\delta(\bar{\Theta}(X), \underline{\Theta}(X)) = \sum_{j=1}^n |\bar{\Theta}(X)(u_j) - \underline{\Theta}(X)(u_j)|$   

$$= \sum_{j=1}^n \bar{\Theta}(X)(u_j) - \sum_{j=1}^n \underline{\Theta}(X)(u_j)$$
 since,  $\underline{\Theta}(X) \subseteq \bar{\Theta}(X)$   

$$= |\bar{\Theta}(X)| - |\underline{\Theta}(X)|$$
  
 Also,  $\delta(\bar{\Theta}(X), \bar{\theta}) = \sum_{j=1}^n |\bar{\Theta}(X)(u_j) - \bar{\theta}(u_j)|$   

$$= \sum_{j=1}^n \bar{\Theta}(X)(u_j) = |\bar{\Theta}(X)|$$
  
 Therefore,  $E_\delta^\Theta(X) = \frac{\delta(\bar{\Theta}(X), \underline{\Theta}(X))}{\delta(\bar{\Theta}(X), \bar{\theta})} = \frac{|\bar{\Theta}(X)| - |\underline{\Theta}(X)|}{|\bar{\Theta}(X)|}$   

$$= 1 - \frac{|\underline{\Theta}(X)|}{|\bar{\Theta}(X)|} = \rho_\theta(X)$$

**Definition 3.12** Let  $(U, \Theta)$  be a fuzzy approximation space. then, a fuzzy set  $X$  on  $U$  is said to be

- i.  $\Theta$ -definable if  $\underline{\Theta}(X) = \bar{\Theta}(X)$

- ii. roughly  $\Theta$ -definable if  $\underline{\Theta}(X) \neq \bar{\theta}$  and  $\bar{\Theta}(X) \neq \bar{U}$
- iii. internally  $\Theta$ -indefinable if  $\underline{\Theta}(X) = \bar{\theta}$  and  $\bar{\Theta}(X) \neq \bar{U}$
- iv. externally  $\Theta$ -indefinable if  $\underline{\Theta}(X) \neq \bar{\theta}$  and  $\bar{\Theta}(X) = \bar{U}$
- v. totally  $\Theta$ -indefinable if  $\underline{\Theta}(X) = \bar{\theta}$  and  $\bar{\Theta}(X) = \bar{U}$

**Theorem 3.13** Let  $(U, \Theta)$  be a fuzzy approximation space. Then,  $\forall X \in \mathcal{F}(U)$ ,

- i.  $0 \leq E_\delta^\Theta(X) \leq 1$
- ii.  $E_\delta^\Theta(X) = 0$ , if  $X$  is  $\Theta$ -definable
- iii.  $E_\delta^\Theta(X) = 1$ , if  $X$  is totally  $\Theta$ -indefinable

*Proof:*

- i. We have,  $\bar{\theta} \subseteq \underline{\Theta}(X) \subseteq \bar{\Theta}(X) \subseteq \bar{U}$ . Hence,  
 $\delta(\bar{\Theta}(X), \underline{\Theta}(X)) \leq \delta(\bar{\Theta}(X), \bar{\theta})$ , by proposition 2.5.

Therefore,  $0 \leq \frac{\delta(\bar{\Theta}(X), \underline{\Theta}(X))}{\delta(\bar{\Theta}(X), \bar{\theta})} \leq 1$ .

That is,  $0 \leq E_\delta^\Theta(X) \leq 1$

- ii. If  $X$  is a  $\Theta$ -definable fuzzy set, then  $\underline{\Theta}(X) = \bar{\Theta}(X)$ . Hence,  $\delta(\bar{\Theta}(X), \underline{\Theta}(X)) = 0$ .

Therefore,  $E_\delta^\Theta(X) = \frac{\delta(\bar{\Theta}(X), \underline{\Theta}(X))}{\delta(\bar{\Theta}(X), \bar{\theta})} = 0$ .

- iii. If  $X$  is a totally  $\Theta$ -indefinable fuzzy set, then  $\underline{\Theta}(X) = \bar{\theta}$  and  $\bar{\Theta}(X) = \bar{U}$ .

Hence,  $E_\delta^\Theta(X) = \frac{\delta(\bar{\Theta}(X), \underline{\Theta}(X))}{\delta(\bar{\Theta}(X), \bar{\theta})} = \frac{\delta(\bar{U}, \bar{\theta})}{\delta(\bar{U}, \bar{\theta})} = 1$ .

**Remark:** Definition 3.11 is also applicable to generalized fuzzy rough sets as it depends only on the fuzzy rough approximations.

#### IV. IMAGE SEGMENTATION USING THE FUZZY ROUGHNESS MEASURE

Image segmentation is a major area of research in digital image processing. Object background segmentation falls under the category of region based image segmentation. In this section, the proposed fuzzy rough uncertainty measure is applied in object background segmentation using grey level thresholding. Here, global thresholding is done using the grey level histogram of the entire image.

Consider a grey level image of order  $m \times n$ . Let  $G$  denote the collection of all pixel values in it. Then,  $G = \{0, 1, \dots, 255\}$ . First, we divide the set of grey level values  $G$  into  $N$  parts and obtain the most frequent grey level value (say  $v_k$ ) in each part by using the histogram of the given image. Corresponding to each  $v_k$ , for  $k = 1, 2, \dots, N$ , we define a fuzzy set  $A_k$  on  $G$ , as

$$A_k(i) = \frac{|g(i) - g(v_k)|}{\max(g(i), g(v_k))} \quad (6)$$

Then,  $P = \{A_k : k = 1, 2, \dots, N\}$  forms a weak fuzzy partition on  $G$ . We define an Z-shaped fuzzy membership function on  $G$  as  $F_G: G \rightarrow [0, 1]$ ,

$$F_G(i) = \begin{cases} 1 & \text{if } i < a \\ \frac{b-i}{b-a}, & \text{if } a \leq i \leq b \\ 0, & \text{otherwise} \end{cases} \quad (7)$$

For each gray level value  $s$ , we define a fuzzy set corresponding to the object in the image as



$$O_s(i) = \begin{cases} F_G(i) & \text{if } i < s \\ F_G(s) & \text{if } i \geq s \end{cases} \quad (8)$$

Let  $\underline{P}(O_s)$  and  $\overline{P}(O_s)$  denote the fuzzy rough approximations of  $O_s$  corresponding to the weak fuzzy partition P. That is;

$$\underline{P}(O_s) = \sup_k \left\{ \min_i \left[ A_k(i), \inf_i (\max(1 - A_k(i), O_s(i))) \right] \right\} \quad (9)$$

$$\overline{P}(O_s) = \sup_k \left\{ \min_i \left[ A_k(i), \sup_i (\max(A_k(i), O_s(i))) \right] \right\} \quad (10)$$

The fuzzy roughness measure corresponding to  $s$  is given by

$$G(s) = \frac{\delta(\overline{P}(O_s), \underline{P}(O_s))}{\delta(\overline{P}(O_s), \overline{\delta})} \quad (11)$$

Here, we use the divergence measure given by  $\delta(X, Y) = \sum_{u \in U} h(X(u), Y(u))$ , where  $h$  represents the Kullback Leibler symmetrical function [13]. The value of  $s$  that makes the fuzzy roughness measure the minimum is selected as the threshold  $c$ . If the minimum is obtained for more than one value of  $s$ , then the largest of such values of  $s$  is selected as  $c$ . Then the image is segmented into a binary image.

### Algorithm

- Step1: Input the grey level image  $G$
- Step2: Find the weak fuzzy partition P
- Step3: For  $s=1:256$ , find the fuzzy set  $O_s$  (eqn 8)
- Step4: Find the fuzzy rough approximations of  $O_s$  (eqns 9 and 10)
- Step5: Find the fuzzy roughness measure  $G(s)$  of  $O_s$  (eqn 11)
- Step6: Find the value  $c$  of  $s$  for which  $G$  is the minimum
- Step7: Segment the image into a binary one using  $c$

### Experimental Results

The histogram based image thresholding algorithm for object background segmentation using the fuzzy roughness measure is implemented using twelve standard test images namely, *baboon*, *barbara*, *boat*, *bridge*, *cameraman*, *house*, *lena*, *mountain*, *peppers*, *rice*, *sailboat* and *zelda*. The original images and the segmented ones using the proposed method, OTSU method and FCM method are presented in figures 1-12.

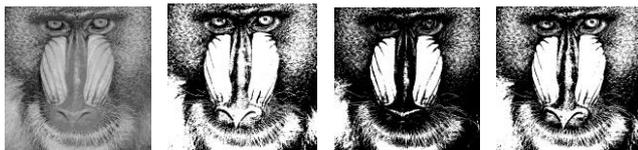


Figure 1: Baboon



Figure 2: Barbara



Figure 3: Boat



Figure 3: Bridge



Figure 5: Cameraman



Figure 6: House



Figure 7: Lena

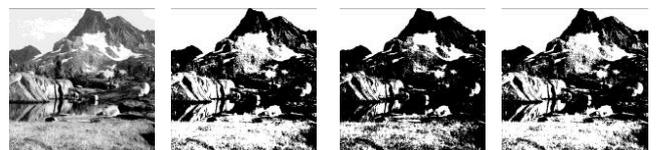


Figure 8: Mountain



Figure 9: Peppers

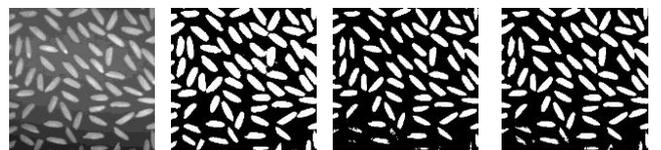


Figure 10: Rice



Figure 11: Sailboat



Figure 12: Zelda

It is observed that the proposed method produces clear binary images in all the twelve instances. It is clear from the figures that the overlapping of the foreground background pixels in the images segmented using the proposed method is lesser than those of the other two methods in most of the cases. Moreover, the RMSE values of the segmented images using the proposed algorithm are found to be the least in comparison with those segmented by OTSU and FCM methods. The values are presented in table 1.

Table 1: RMSE Values

Sl.No.	Image	Proposed	FCM	OTSU
1	Baboon	<b>10.4913</b>	12.8914	11.0631
2	Barbara	<b>10.6785</b>	13.142	11.2947
3	Boat	8.3446	13.2356	<b>7.3552</b>
4	Bridge	<b>11.3048</b>	14.0448	12.5354
5	Cameraman	8.6786	9.9101	<b>8.5900</b>
6	House	<b>11.2745</b>	12.5152	12.3645
7	Lena	<b>9.9071</b>	13.7681	10.3126
8	Mountain	<b>10.4935</b>	11.9843	10.5766
9	Peppers	<b>10.5498</b>	11.7984	11.0332
10	Rice	<b>12.7157</b>	13.6784	13.4477
11	Sailboat	<b>10.1063</b>	12.5904	10.6945
12	Zelda	<b>11.2745</b>	12.5152	12.3645

## V. CONCLUSION

Measures of uncertainty are proved to be effective tools for image segmentation. In this paper, new fuzzy rough uncertainty measures have been defined on fuzzy approximation spaces. A histogram based image thresholding algorithm using the fuzzy roughness measure is developed and experimented with different images. The segmented images of twelve test images using the proposed algorithm have been compared with those of OTSU method and FCM method. It is observed that the overlapping of the foreground background pixels in the images segmented using the proposed method is lesser than those of the other two methods. Further, the proposed algorithm produces images having the least root mean square error values in ten out of twelve cases. Thus, the proposed image segmentation algorithm can be used as an alternative for OTSU and FCM methods which are two popular methods used for binary segmentation.

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