

Modeling & Performance Scrutiny of Maximum Power Extraction Strategy in PMSG based Wind Energy Transformation System



Beena Kumari, Deepa Mehta

Abstract: Energy from wind is turning out to be a very promising alternative source technology in present and future power sector as it is environment-friendly and long-lasting with technological enhancements. Moreover, it occupies less space and has relative cost competitiveness. In the utility grid, the penetration of wind energy systems is expanding as the research progresses to capture greatest available wind power and operate the wind turbine (WT) with maximum possible aerodynamic efficiency. For this to accomplish a tracking controller is required to extract greatest wind power at all instants in the wide range of wind speeds. This paper presents a simple control technique for optimal power extraction from cut-in to rated wind speed range by sensing the dc-link power. It also embraces mathematical modeling of wind energy conversion system. The proposed algorithm shows excellent tracking capability under fluctuating wind conditions as revealed by power speed characteristic obtained in a wind energy system. The effectiveness of proposed strategy is verified by Matlab simulation.

Keywords: Wind aerodynamics, Maximum Power Point Tracking, Permanent Magnet Synchronous Generator

I. INTRODUCTION

Wind energy is one of the most favorable sources of sustainable energy due to its minimal environmental effect and abundant availability. Wind power technology has developed rapidly in recent years and so, it is considered as the most promising alternative source of energy. Wind power farms are accelerating at an exponential rate and is expected to devote 20% of global energy by 2030 [1]-[2]. However, due to the unpredictable and unstable nature of wind with highly stochastic and rapid time varying pattern, it confronts challenge for extracting maximum power at each and every instant of wind speed variations. So, an effective maximum power extraction strategy is called for satisfying the needs of optimal power capture and improved system aerodynamic efficiency. The various configuration of wind energy conversion system comprises of fixed speed or variable speed wind turbine (VSWT) driven directly or indirectly with synchronous or asynchronous generator [3]-[4]. Among these, variable speed wind turbine coupled with direct-driven

permanent magnet synchronous generator (PMSG) is the most suited configuration. This is because VSWT furnish high energy conversion efficiency with improved power quality and reduced mechanical stresses. The system complexity and additional cost and losses due to power-electronic converters are the drawbacks of VSWT. These hurdles are counterbalanced by the usage of direct driven PMSG that incorporates gearbox exclusion, low speed-high torque output, eradication of ancillary excitation system or cooling system, low maintenance and operating cost, design flexibility and stable performance with power-electronic converters/ inverters [5]. Hence, this configuration is becoming more popular for large scale and off-shore wind applications. With the rising exploration of wind energy systems in utility grid, it becomes necessary to efficiently capture maximum output power from wind turbine at all instants in wide range of wind speeds. This can be accomplished by incorporating a tracking strategy for power maximization that regulates rotor speed as per MPP for different wind speeds [6]-[10]. Enormous research and development work is carried with Traditional and advanced MPPT methodologies for achieving excellent tracking under wind speed variations. Among the various techniques discussed so far in literature includes measurement of wind speed by anemometer as in Tip-speed ratio (TSR) or store optimal speed-power values for different speeds in look-up table as in Optimal Torque Control (OTC) and Power Signal Feedback (PSF). These techniques were based on measurement of mechanical parameters like wind speed or wind turbine parameters [11]-[14]. Such strategies revealed negative performance due to aging and environmental impact which made research towards advanced techniques. Advanced techniques [15]-[18] get differentiated from traditional techniques by measurement of electrical parameters like voltage, current or power that are both easy, accurate and cost-effective to measure. Moreover, they do not need mathematical modeling of the physical system and are not affected by system parameter variations. The need of mechanical sensors is also not required for them. The various MPPT techniques included in this category are Hill Climb Search (HCS), Incremental Conductance (INC), Optimum Relation Based (ORB), Soft computing techniques such as Fuzzy logic control (FLC), Artificial Neural Network (ANN), Adaptive Neuro Fuzzy Inference System (ANFIS) and Metaheuristic optimization techniques such as Democratic Joint Operations Algorithm (DJOA), Particle Swarm Optimisation (PSO), Whale Optimisation Algorithm (WOA), Grey Wolf Optimisation (GWO).

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This paper proposes a maximum power extraction strategy based on Hill Climb Search and Optimal Torque strategy for PMSG based WECS by controlling the dc link power output at the rectifier terminals.

It makes use of single IGBT based active semiconductor switch to regulate generator torque for maximum power extraction.

It is a cheap and less complex technique for wind energy systems. This research paper is presented as follows. Section II includes the modeling of wind energy conversion system, Section III presents the concept of MPPT with power speed characteristic plot, Section IV gives the representation and analysis of maximum power extraction strategy with matlab Simulink model and section V concludes the article.

II. MODELING OF WECS

Wind aerodynamic system incorporates a wind turbine linked to electrical generator through the shaft of turbine. The electrical output is regulated and controlled by power-electronic interface including rectifier, boost converter, inverter and then integrated with utility grid [19]-[20].

A. Wind turbine model

Wind turbines convert the available wind power into mechanical power (P_m) as given by eq. (1)

$$P_m = 0.5\rho C_p(\lambda, \beta) A v^3 \quad (1)$$

$$C_p(\lambda, \beta) = 0.73 \left(\frac{151}{\lambda_i} - 0.58\beta - 0.002\beta^{2.14} - 13.2 \right) e^{-\frac{13.2}{\lambda_i}} \quad (2)$$

$$\frac{1}{\lambda_i} = \frac{1}{\lambda + 0.02\beta} - \frac{0.03}{1 + \beta^3} \quad (3)$$

$$\lambda = \frac{R\omega_m}{v} \quad (4)$$

$$P_{max} = \frac{v}{2} \rho A \left(\frac{\omega_m R}{\lambda_{opt}} \right)^3 C_{p_{opt}} \quad (5)$$

Where C_p is power coefficient which is a function of pitch angle β and TSR λ , R is the blade radius in meters and A is the blade swept area in m^2 , v is the wind velocity in m/s , ρ is the air density in Kg/m^3 , ω_m is the rotor speed in rad/s . The optimum parameters for maximum power P_{max} are λ_{opt} and $C_{p_{opt}}$. Ceaseless working of wind turbine guarantees to achieve optimal power at any wind speed as explained by non-linear power-speed characteristic of wind turbine in section III.

B. PMSG model

PMSG transforms mechanical energy obtained from wind turbine into electrical energy. The model of Permanent Magnet Synchronous Machine (PMSM) is established in d-q reference frame [18]-[19] with the voltage and torque equations expressed as

$$\begin{pmatrix} v_{sd} \\ v_{sq} \end{pmatrix} = -R_s \begin{pmatrix} i_{sd} \\ i_{sq} \end{pmatrix} - \frac{d}{dt} \begin{pmatrix} L_d i_{sd} \\ L_q i_{sq} \end{pmatrix} + \omega_e \begin{pmatrix} -L_q i_{sq} \\ L_d i_{sd} + \psi_f \end{pmatrix} \quad (6)$$

$$T_e = p[(L_d - L_q) i_{sd} i_{sq} + i_{sq} \psi_f] \quad (7)$$

where v_{sd} , v_{sq} , i_{sd} , i_{sq} are the generator terminal d-q voltages and d-q currents, L_d and L_q are the d-q inductances, R_s is the resistance, ψ_f is the permanent magnet flux that links the stator windings and T_e is the electromagnetic torque in Nm. The dynamics of shaft system for direct-drive train of PMSG variable speed wind turbine is

modeled as:

$$j \frac{d\omega_m}{dt} + D\omega_m = T_m - T_e \quad (8)$$

Where j is the generator inertia, D is the coefficient of rotor damping, T_m is the mechanical torque developed by wind turbine, ω_m and ω_e are the mechanical and electrical speeds related by number of poles, P as

$$\omega_e = \frac{P}{2} \omega_m \quad (9)$$

C. Diode Bridge Rectifier

The function of diode bridge rectifier at the output terminals of PMSG is to convert three phase AC voltage into DC voltage. The average output voltage of the rectifier is given by

$$V_{avg} = \frac{3\sqrt{3}V_{ph}}{\pi} \quad (10)$$

Where V_{ph} is the peak value of the phase voltage of the PMSG.

D. Boost Converter

The rectified DC voltage is converted into DC of desired magnitude with the help of boost converter that consists of inductor, IGBT switch, diode and capacitor as shown in Fig.1. It works in continuous conduction mode with the design expressions as given:

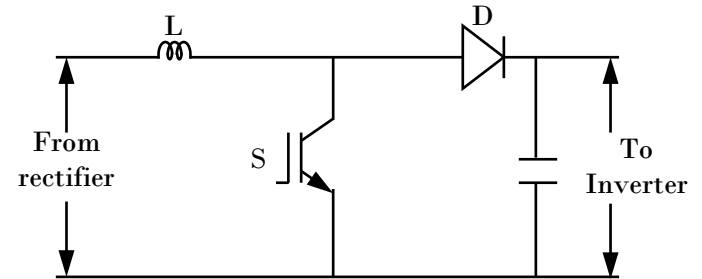


Fig. 1. Boost Converter Circuit [20]

The average output voltage of converter (V_{DC}) is

$$V_{DC} = \frac{V_{avg}}{(1-k)} \quad (11)$$

$$L = \frac{kV_{avg}}{f_s \Delta I} \quad (12)$$

$$C = \frac{kI}{f_s \Delta V_c} \quad (13)$$

Where ΔI the peak to peak ripple is current of inductor, ΔV_c is the peak to peak ripple voltage of capacitor, k is the duty ratio of the switch S and f_s is the switching frequency.

III. MAXIMUM POWER POINT TRACKING

Wind energy conversion system employ maximum power extraction strategy for sustainable power output. The power output from wind turbine has four operating zones when plotted with wind velocity as shown in fig.2. The power obtained in zones 1 and 4 is not reliable as the wind is too low in first zone and too high in last zone that can cause damage the wind turbine. Zone 2 is the optimal zone for maximum power extraction in wind energy systems. The power output is



limited in zone 3 by pitch angle control for safety of turbine.

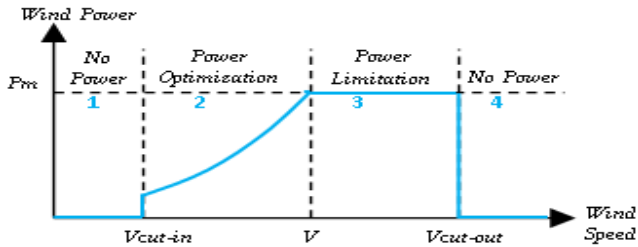


Fig. 2. Operating Zones of Wind Turbine Power-Speed Curve [8]

The aim of maximum power point tracking controller is to trace the curve obtained by connecting maximum power points at different wind speeds. This is achieved by regulating rotor speed to optimal speed under wind speed variations [21]-[23]. The expression for optimum rotor speed is given by

$$\omega_{m_opt} = \frac{\lambda_{opt} v}{R} \quad (14)$$

This results in maximum power expression as:

$$P_{m_opt} = 0.5 \rho A C_p C_{p_opt} \left(\frac{\omega_{m_opt} R}{\lambda_{opt}} \right)^3 = K_{opt} (\omega_{m_opt})^3 \quad (15)$$

Where

$$K_{opt} = 0.5 \rho A C_p C_{p_opt} \left(\frac{R}{\lambda_{opt}} \right)^3 \quad (16)$$

And maximum torque as:

$$T_{m_opt} = K_{opt} (\omega_{m_opt})^2 \quad (17)$$

With these expressions, power speed curve is plotted for different speeds and optimal active power curve is achieved [24]-[27]. The concept of maximum power point tracking is explained by finding out power at different rotor speeds (varied from 25 rpm to 500 rpm) for a particular wind speed. It is observed that maximum power at any wind speed is obtained at a particular rotor speed. Table I shows the maximum power output of 1101W at 125 rpm rotor speed when the wind speed was taken as 6m/s. In the same way, maximum power at specific rotor speed is determined in Table II and Table III at wind speeds of 12 m/s and 14 m/s. Pitch angle is changed in Table III to keep the wind turbine working at rated speed (275 rpm) and rated power (8500 W) for given study All other outputs are summarized in Table IV.

Table- I: Power Output for rotor speed variation (25 rpm to 500rpm) for wind speed at 6 m/s

rotation al speed, rev/min	angular speed, rad/s	wind velocity, m/s	pitch angle, deg	tip-speed ratio	perf. coefficient	power, W	
n	wr	Vw	β	λ	λi	Cp	p6
25	2.6	6	0	1.09	1.13	0.00	0
50	5.2	6	0	2.18	2.33	0.01	36
75	7.9	6	0	3.27	3.63	0.13	331
100	10.5	6	0	4.36	5.02	0.32	803
125	13.1	6	0	5.45	6.52	0.43	1101
150	15.7	6	0	6.55	8.14	0.41	1036
175	18.3	6	0	7.64	9.91	0.23	593
200	20.9	6	0	8.73	11.82	-0.07	-167
225	23.6	6	0	9.82	13.92	-0.46	-1164
250	26.2	6	0	10.91	16.22	-0.91	-2322
275	28.8	6	0	12.00	18.75	-1.41	-3583
300	31.4	6	0	13.09	21.56	-1.93	-4901
325	34.0	6	0	14.18	24.68	-2.45	-6243
350	36.7	6	0	15.27	28.19	-2.98	-7585
375	39.3	6	0	16.36	32.14	-3.50	-8910
400	41.9	6	0	17.45	36.64	-4.01	-10207
425	44.5	6	0	18.54	41.80	-4.51	-11468
450	47.1	6	0	19.64	47.78	-4.99	-12690
475	49.7	6	0	20.73	54.80	-5.45	-13869
500	52.4	6	0	21.82	63.15	-5.90	-15004

Table- II: Power Output for rotor speed variation (25 rpm to 500rpm) for wind speed at 12 m/s

rotation al speed, rev/min	angular speed, rad/s	wind velocity, m/s	pitch angle, deg	tip-speed ratio	perf. coefficient	power, W	
n	wr	Vw	β	λ	λi	Cp	p12
25	2.6	12	0	0.55	0.55	0.00	0
50	5.2	12	0	1.09	1.13	0.00	0
75	7.9	12	0	1.64	1.72	0.00	25
100	10.5	12	0	2.18	2.33	0.01	289
125	13.1	12	0	2.73	2.97	0.06	1141
150	15.7	12	0	3.27	3.63	0.13	2651
175	18.3	12	0	3.82	4.31	0.22	4546
200	20.9	12	0	4.36	5.02	0.32	6423
225	23.6	12	0	4.91	5.76	0.39	7923
250	26.2	12	0	5.45	6.52	0.43	8805
275	28.8	12	0	6.00	7.32	0.44	8940
300	31.4	12	0	6.55	8.14	0.41	8288
325	34.0	12	0	7.09	9.01	0.34	6870
350	36.7	12	0	7.64	9.91	0.23	4741
375	39.3	12	0	8.18	10.84	0.10	1978
400	41.9	12	0	8.73	11.82	-0.07	-1339
425	44.5	12	0	9.27	12.85	-0.25	-5127
450	47.1	12	0	9.82	13.92	-0.46	-9309
475	49.7	12	0	10.36	15.04	-0.68	-13813
500	52.4	12	0	10.91	16.22	-0.91	-18576

Table- III: Power Output for rotor speed variation (25 rpm to 500rpm) for wind speed at 14 m/s

rotation al speed, rev/min	angular speed, rad/s	wind velocity, m/s	pitch angle, deg	tip-speed ratio	perf. coefficient	power, W	
n	wr	Vw	β	λ	λi	Cp	p14
25	2.6	14	5.3	0.47	0.57	0.00	0
50	5.2	14	5.3	0.94	1.04	0.00	0
75	7.9	14	5.3	1.40	1.51	0.00	10
100	10.5	14	5.3	1.87	1.98	0.00	127
125	13.1	14	5.3	2.34	2.44	0.02	569
150	15.7	14	5.3	2.81	2.91	0.05	1485
175	18.3	14	5.3	3.27	3.38	0.09	2828
200	20.9	14	5.3	3.74	3.85	0.14	4406
225	23.6	14	5.3	4.21	4.32	0.19	5985
250	26.2	14	5.3	4.68	4.79	0.23	7355
275	28.8	14	5.3	5.14	5.25	0.26	8361
300	31.4	14	5.3	5.61	5.72	0.28	8908
325	34.0	14	5.3	6.08	6.19	0.28	8949
350	36.7	14	5.3	6.55	6.66	0.26	8474
375	39.3	14	5.3	7.01	7.13	0.23	7499
400	41.9	14	5.3	7.48	7.60	0.19	6055
425	44.5	14	5.3	7.95	8.07	0.13	4185
450	47.1	14	5.3	8.42	8.54	0.06	1932
475	49.7	14	5.3	8.88	9.00	-0.02	-658
500	52.4	14	5.3	9.35	9.47	-0.11	-3538

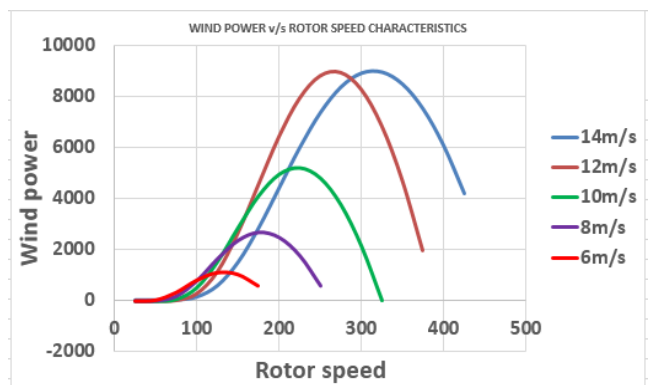


Fig. 3. Power-speed curve

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Vw(m/s)	Wr(rad/s)	n(rpm)	β (deg)	power(W)	
6	15.7	125	0	1101	MPPT control of WT
7	15.7	150	0	1771	
8	20.9	175	0	2658	
9	20.9	200	0	3789	
10	20.9	225	0	5194	
11	26.2	250	0	6902	
12	28.8	275	0	8940	Rated speed & Rated power of WT
13	34	325	3	8974	Pitch angle control for WT
14	34	325	5.3	8949	
15	34	325	7.1	8978	
16	34	325	8.7	8894	
17	34	325	10	8931	
18	34	325	11.2	8886	

Table- IV: Summary of Power Output at different wind speeds

IV. SIMULINK MODEL AND ANALYSIS

The model of PMSG based wind energy conversion system is prepared using Simpowersystem Toolbox of Matlab Simulink software as shown in Fig.4. The maximum power extraction strategy is represented in Fig.5. The wind turbine and PMSG parameters are shown in Table V. The sampling time used for simulation is $50\mu s$. Fig.6 shows the step variations of wind speed at different instants. It is observed from the power-speed characteristic obtained in Fig.7 that the maximum power extraction strategy efficiently tracks the maximum power with wind speed variations. So, the proposed strategy can be used to extract maximum power from variable speed wind turbine under fluctuating wind conditions.

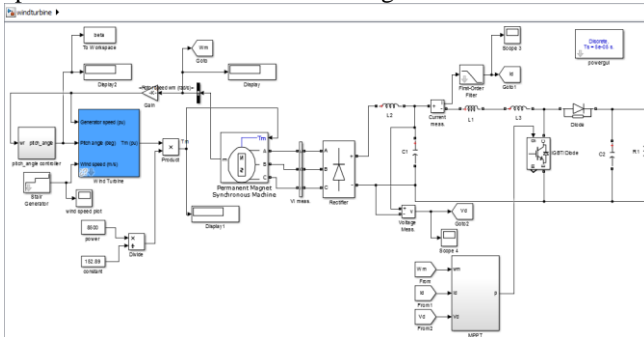


Fig. 4. WECS Simulink model

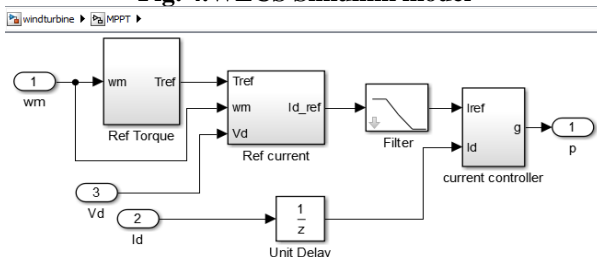


Fig. 5. MPPT model

Table- V: Wind Turbine and PMSG values

Parameters	Values
Wind Turbine Parameters	
Base wind speed	12m/s
Wind Turbine	8.5 KW
Load Power	10Kw
PMSG Parameters	
Stator resistance (Rs)	0.425ohms
Inductance (Ld, Lq)	0.0082 H
Flux linkage	0.433V.s
Voltage constant	392.684 v peak L-L
Torque Constant	3.2475 N.m
Inertia Constant	0.01197 kg.m ²
Friction factor	0.001189N.m.s
Poles	5
Filter Parameters	
R	1ohm
L	0.1mH
C	100 μ F

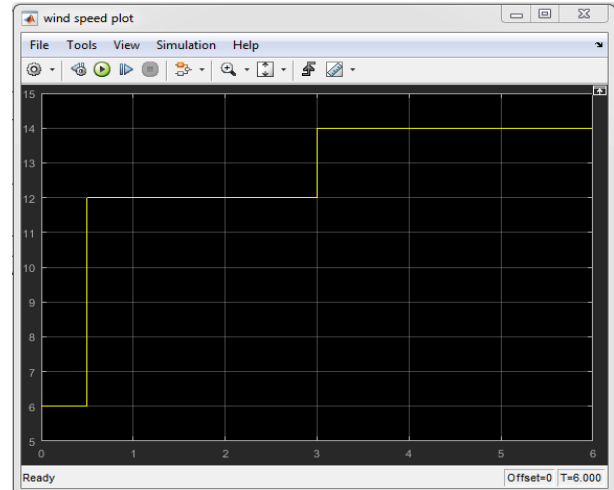


Fig. 6. Wind speed input plot

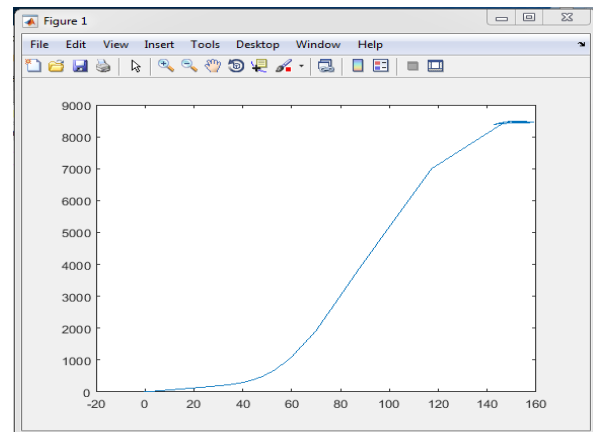


Fig. 7. Optimal Power-Speed Curve showing maximum power tracking

V. CONCLUSION

A maximum power extraction strategy for PMSG based wind energy conversion system is presented and simulated for variable wind speed profile. The proposed strategy have achieved the objective of extracting maximum power from any wind speed without prior knowledge of wind speed or rotor speed. Wind turbine aerodynamic attributes are also not required for this strategy to progress.

The system behaves efficiently under rapid variations of wind conditions as revealed by the power-speed characteristic obtained in Matlab Simulink model. Future application may include innovation of some system technology to generate more power at low wind speeds, use of multi-phase PMSG for effective fault tolerant capability and proper grid connection of PMSG based WECS.

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Beena Kumari received the B.E degree in electrical engineering from Saurashtra University, Rajkot, Gujarat in 2003 and M.Tech in Power Electronics, Electrical Machines and Drives from MDU, Rohtak, Haryana in 2010. She is now a Research Scholar at G.D Goenka University, Gurugram, Haryana since 2017. She has about eight years of teaching experience at an engineering

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