

Application of Dynamic Voltage Restorer for Enhancing low voltage Ride-through capability of Doubly Fed Induction Generator

The Grid side controller does this function. Here also grid side field-oriented control is used. The control of the dc link voltage is accomplished through the proper selection of required direct axis current and the perpendicular component of current controls the reactive power [2]. Figure 3 shows the block diagram of Grid side controller. For analysis purpose the equivalent circuit of DFIG is simplified as shown in Figure.4.[3]From the equivalent circuit shown vector diagram is obtained as shown in Figure.5

torque occurs as in Figure.8, Figure.7, and Figure.9. During sag period,entire high rotor current circulates through the crow bar,there by protecting the rotor side converter.

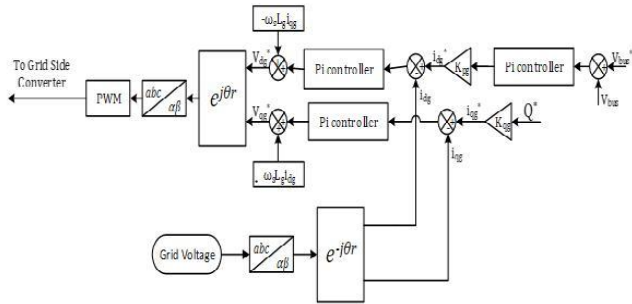


Fig. 3. Grid side control of DFIG

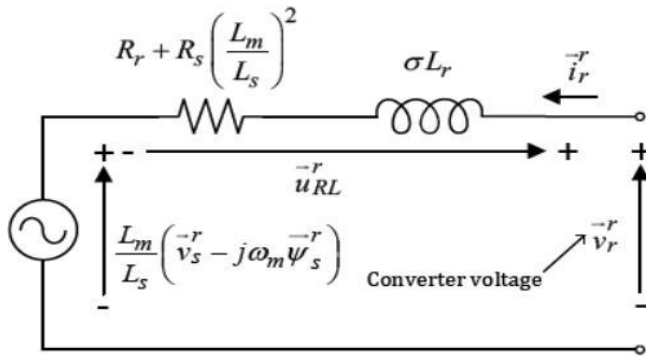


Fig. 4. DFIG Simplified Equivalent circuit.

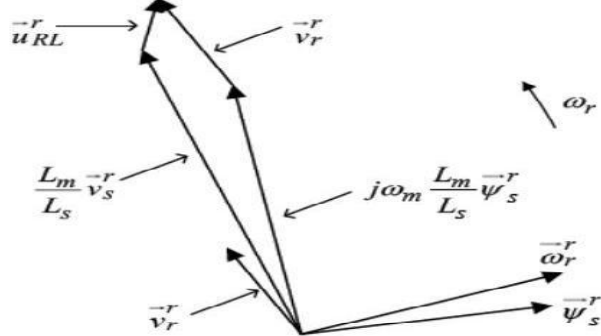


Fig. 5. DFIG Voltage Vector diagram

III. DFIG WITH SYMMETRICAL VOLTAGE DIP

$$\frac{d\phi_s}{dt} = V_s - \frac{R_s}{L_s} \phi_s + R_s \frac{L_m}{L_s} i_r \quad (1)$$

$$V_r = \frac{L_m}{L_s} (V_s - j\omega_m \phi_s) + \left[R_r + \left(\frac{L_m}{L_s} \right)^2 R_s \right] i_r + \sigma L_r \frac{di_r}{dt} \quad (2)$$

The equations 1 and 2 show the variation of stator flux and rotor voltage. The analysis is conducted by means of simulation using MATLAB, based on 2MW Wind turbine based DFIG Wind turbine system. Here the Voltage dip occurs at a time period equals 3 seconds, as shown in Figure. 6, when the dip occurs the grid voltage is only 10% of rated voltage. The crowbar is activated at the same time, connecting the additional resistance path in the machine. During the first instant of the dip, peak stator and rotor current and large

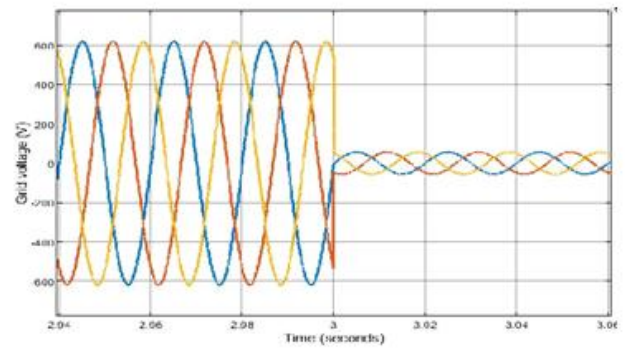


Fig. 6. Grid voltage with Symmetrical voltage sag

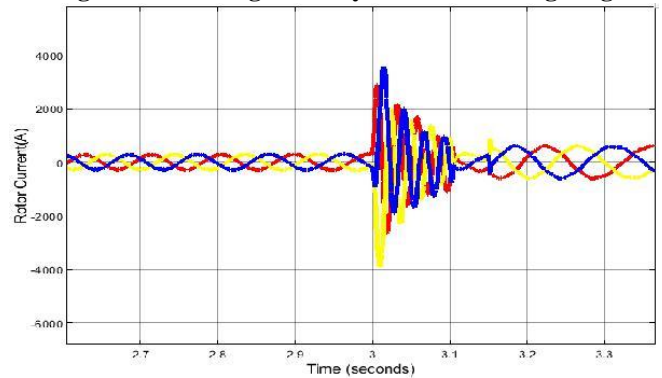


Fig. 7 DFIG Rotor current with Symmetrical voltage sag.

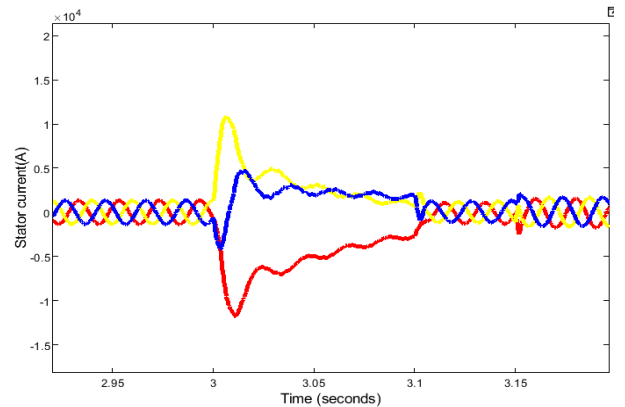


Fig. 8 DFIG Stator current with Symmetrical voltage sag

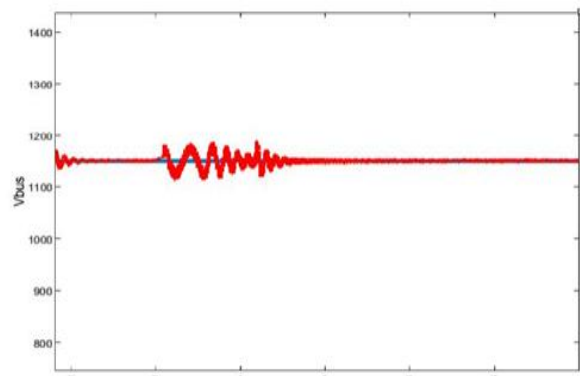


Fig.9 DC bus voltage with symmetrical voltage sag

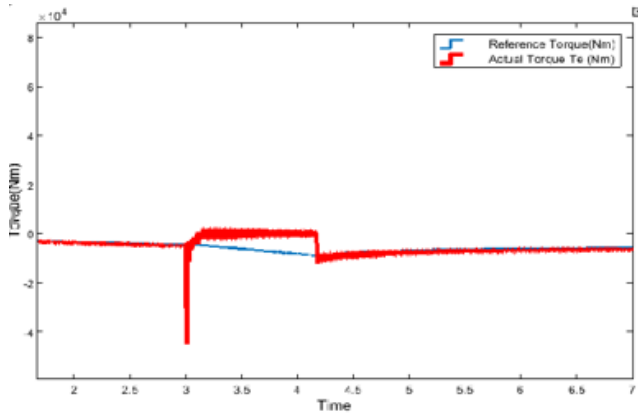


Fig. 10 DFIG Torque developed with symmetrical sag..

IV. DFIG WITH SYMMETRICAL VOLTAGE SAG AND DVR CONTROL

As Explained in the preceding section even though a protective resistor is used the magnitude of stator and rotor current is very high during sag period. Also a large fluctuation is their in the dc link voltage.[4] In this work Dynamic Voltage Restorer is used for operating DFIG under voltage sag conditions. Here a three phase rectifier properly charges the capacitor. The losses in the single phase injection transformer is not considered in this work

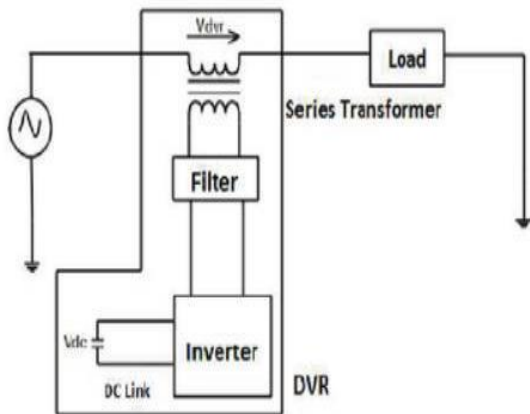


Fig.11 DVR Basic Circuit

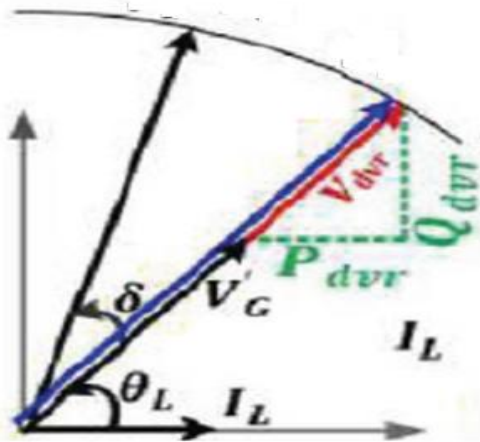


Fig.12 DC bus voltage with symmetrical voltage sag

A basic circuit of Dynamic Voltage Restorer is shown in Figure 11. When the net work voltage reduces due to reason such as sudden increase in load etc, the DVR injects a voltage in such away that the desired network voltage can be

maintained. The vector diagram shows the required injected voltage for correcting a given amount of sag. The grid phase angle can be found out using Phase locked loop. Fig.12 shows the vector diagram with series voltage injection. The magnitude of the injected voltage is given by Eqn.3, in which ' V_s ' represent the grid voltage, ' V_{dfig} ' represent the DFIG terminal voltage. ' V_{dvr} ' is the injected voltage by the DVR. The series compensation is achieved by injecting the required amount of voltage to the grid using the three single phase transformer. The monitoring of dc link voltage is very essential due to the reason that active power transfer is happening through dc link. A phase locked loop is employed to obtain the phase angle for injecting the voltage at correct phase angle. The control generates the 'dq' reference which is transformed to the three phase stationary reference frame value in order to generate correct control signal for the PWM modulation. To verify the effectiveness of the proposed method of control of DVR simulation has been done using MATLAB on a 2MW DFIG system, by choosing a wind speed of 11m/s. For simulation purpose maximum sag of 90% is given from 3 seconds to a time period of 1.2 seconds. Figure.13 shows the variation of grid voltage, after the sag, the voltage increases in a ramp manner. Figure.14 shows the variation of DVR injected voltage. It is evident from the figure that as the grid voltage increases after the sag the injected voltage from the DVR decreases. Figure 15 shows the DFIG terminal voltage after compensation using Dynamic voltage restorer. Figures 16 and 17 shows the variation in rotor current and dc bus voltage. On comparison with the value of rotor current without compensation it is clear that the value of rotor current reduces due to compensation.

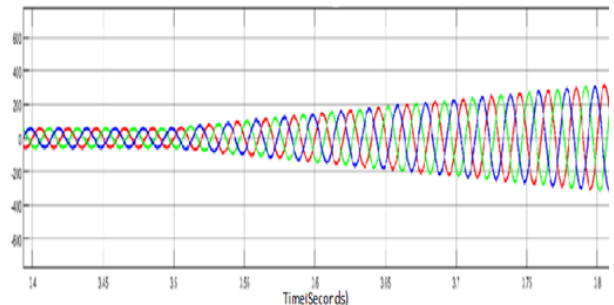


Fig.13 Grid Voltage.

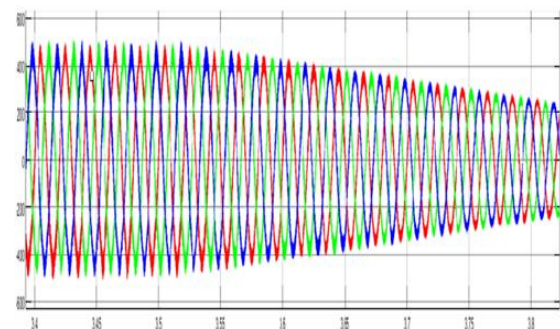


Fig.14 DVR Injected voltage with symmetrical sag

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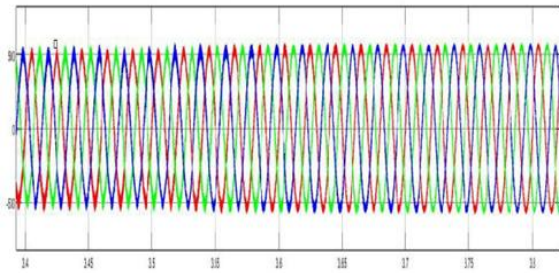


Fig.15 DFIG Terminal voltage with symmetrical sag

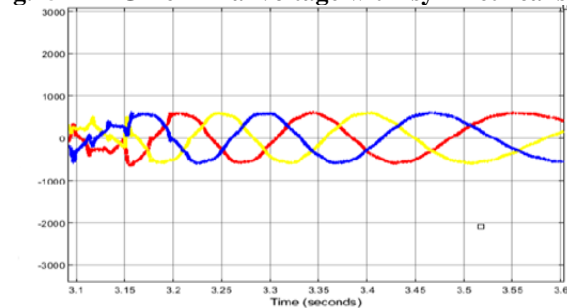


Fig.16 DFIG Rotor current with symmetrical sag

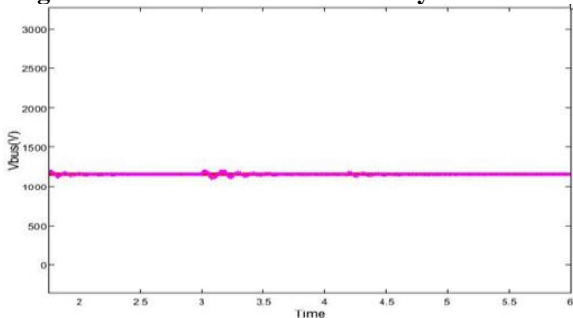


Fig.17 DFIG DC bus voltage with symmetrical sag

$$V_{dcr} = \sqrt{V_s^2 + V_{dfig}^2 - 2V_s V_{dfig} \cos \delta} \quad (3)$$

V. CONCLUSION

This paper gives behavior of grid connected Doubly Fed induction Generator under symmetrical network unbalance voltage. Also here the Authors analyses the application of Dynamic Voltage Restorer to improve the fault ride-through capability of DFIG based wind Turbine system. To show the complete behavior of DFIG, during grid voltage disturbances, simulation result of 2 MW DFIG system are presented. From the various result obtained through MATLAB simulation it is understood that the proposed control method is very effective.

APPENDIX-I

2 kW, 690V, 50Hz generator parameters

Stator resistance, $R_s = 0.19\Omega$

Rotor resistance, $R_r = 0.39\Omega$

Number of Poles, $P = 4$

Magnetizing inductance, $L_m = 4 \text{ mH}$

Stator leakage inductance, $L_{ls} = 0.21 \text{ mH}$.

Rotor leakage inductance, $L_{lr} = 0.6 \text{ mH}$

Stator inductances = 4.21 mH

Rotor inductance = 4.6 mH

Moment of inertia $J = 0.0226 \text{ Nm/(rad s)}$

Damping constant = $0.2 \text{ Nm/(rad s}^2\text{)}$

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AUTHORS PROFILE



T.Samina. was born in Kollam, Kerala. She received her B.Tech degree in Electrical & Electronics Engineering, from Kerala University, and her M.Tech degree in Power Systems from National Institute of Technology, Tiruchirappalli. Currently she is pursuing her Ph.D. degree in Power systems from Kerala University. Her employment experience includes Industrial experience in Power system Field and Teaching experience. Currently she is working as associate Professor, in College of Engineering, Thiruvananthapuram. Her area of interest includes Power systems, Wind power Technology, Power Electronics etc..



A.Bisharthu Beevi. Was born in Kerala. She received her B.Tech degree in Electrical & Electronics engineering in 1986, M.Tech degree in Power Systems in 2000 and Ph.D degree in Power systems in 2011, from Kerala University. She has started her career as Lecturer in Electrical Engineering in 1992 at Govt. Engineering College, Kannur and served in various engineering colleges across Kerala. She has a total of 29 years of Teaching Research and Administrative Experience. She has published more than 65 papers in reputed journals and conferences. Her research field includes power Systems, Power Electronics etc..

S.RamaIyer. was born in Kerala. He Received his M.Tech and Ph.D Degree in Power Systems, from Indian institute of Technology, Delhi. He served as professor in Electrical Department, and as Dean in College of Engineering, Thiruvananthapuram. His research area includes Power Systems, Power Electronics, etc. He is the owner of a large number of publications in various reputed journals in the field of Power systems. Currently he retired from Government service and guiding a number of Research Scholars.